



Software Implementation of I²C™ Bus Master

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INTRODUCTION

This application note describes the software implementation of I²C interface routines for the PIC16CXXX family of devices. Only the master mode of I²C interface is implemented in this application note. This implementation is for a single master communication to multiple slave I²C devices.

Some PIC16CXXX devices, such as the PIC16C64 and PIC16C74, have on-chip hardware which implements the I²C slave interface, while other PIC16CXXX devices, such as the PIC16C71 and PIC16C84, do not have the same on-chip hardware.

This application note does not describe the I²C Bus specifications and the user is assumed to have an understanding of the I²C Bus. For detailed information on the bus, the user is advised to read the I²C Bus Specification document from Philips/Signetics (order number 98-8080-575). The I²C Bus is a two-wire serial bus with multiple possible masters and multiple possible slaves connected to each other through two wires. The two wires consists of a clock line (SCL) and a data line (SDA) with both lines being bi-directional. Bi-directional communication is facilitated through the use of wire and connection (the lines are either active-low or passive high). The I²C Bus protocol also allows collision detection, clock synchronization and hand-shaking for multi-master systems. The clock is always generated by the master, but the slave may hold it low to generate a wait state.

In most systems the microcontroller is the master and the external peripheral devices are slaves. In these cases this application note can be used to attach I²C slaves to the PIC16CXXX (the master) microcontroller. The multi-master system is not implemented because it is extremely difficult to meet all the I²C Bus timing specifications using software. For a true slave or multi-master system, some interface hardware is necessary (like START & STOP bit detection).

In addition to the low level single master I²C routines, a collection of high level routines with various message structures is given. These high level macros/routines can be used as canned routines to interface to most I²C slave devices. As an example, the test program talks to two Serial EEPROMs (Microchip's 24LC04 and 24LC01).

IMPLEMENTATION

Two levels of software routines are provided. The low-level routines "i2c_low.asm" are provided in Appendix A and the high level routines "i2c_high.asm" are provided in Appendix B.

The messages passed (communicated on the two wire network) are abbreviated and certain notation is used to represent Start, Stop and other conditions. These abbreviations are described in Table 1.

TABLE 1: DESCRIPTION OF ABBREVIATIONS USED

Abbreviations	Explanation
S	Start Condition
P	Stop Condition
SivAR	Slave Address (for read operation)
SivAW	Slave Address (for write operation)
A	Acknowledge condition (positive ACK)
N	Negative Acknowledge condition (NACK)
D	Data byte, D[0] represents byte 0, D[1] represents second byte

Message Format

In the high level routines, the basic structure of the message is given. Every I²C slave supports one or more message structures. For example, Microchip's 24LC04 Serial EEPROM supports the following message (to write a byte to Serial EEPROM at current address counter) S-SlvAW-A-D-A-P which basically means the following sequence of operations are required:

- a) Send Start Bit
- b) Send Slave Address for Write Operations
- c) Expect Acknowledge
- d) Send Data Byte
- e) Expect Acknowledge
- f) Issue a STOP Condition

Slave Address

Both 10-bit and 7-Bit addressing schemes are implemented as specified by the I²C Bus specification. Before calling a certain sub-routine (high level or low-level), the address of the slave being addressed must be loaded using either "LOAD_ADDR_8" (for 7-bit address slaves) or "LOAD_ADDR_10" macro (for 10-bit address slaves). These macros not only load the address of the slaves for all the following operations, but also setup conditions for 7- or 10-bit addressing modes. See the macros section for more details.

CLOCK STRETCHING

In the I²C Bus, the clock (SCL line) is always provided by the master. However, the slave can hold the line low even though the master has released it. The master must check this condition and wait for the slave to release the clock line. This provides a built-in wait state for the I²C Bus. This feature is implemented and can be turned on or off as an assembly time option (by configuring the `_ENABLE_BUS_FREE_TIME` flag to be TRUE or FALSE). If the clock is held low for too long, say 1 ms, then an error condition is assumed and a T0CKI interrupt is generated.

ARBITRATION

The I²C Bus specifies both bit-by-bit and byte mode arbitration procedures for multi-master systems. However, the arbitration is not needed in a single master system, and therefore is not implemented in this application note.

HARDWARE

Two I/O pins are used to emulate the Clock Line, SCL, and the Data Line, SDA. In the example test program, RB0 is used as the SCL line and RB1 as the SDA line. On initialization, these I/O lines are configured as input pins (tri-state) and their respective latches are loaded with '0's. To emulate the high state (passive), these lines are configured as inputs. To emulate the active low state, the pins are configured as outputs (with the assumption of having external pull-up resistors on both lines).

For devices that have the on-chip I²C hardware (SSP module), slope control of the I/O is implemented on the SCK and SDA pins. For software not implemented on the SCK and SDA pins of the SSP module, external components for slope control of the I/O may be required by the system.

I²C ROUTINES

Status Register (File Register “Bus_Status”)

The bit definitions of the status register are described in the table given below. These bits reflect the status of the I²C Bus.

Bit #	Name	Description
0	_Bus_Busy	1 = Start Bit transmitted 0 = STOP condition
1	_Abort	It is set when a fatal error condition is detected. The user must clear this bit. This bit is set when the clock line, SCL, is stuck low.
2	_Txmt_Progress	1 = transmission in progress
3	_Rcv_Progress	1 = reception in progress
4	_Txmt_Success	1 = transmission successfully completed 0 = error condition
5	_Rcv_Success	1 = reception successfully completed 0 = error condition
6	_Fatal_Error	1 = FATAL error occurred (the communication was aborted).
7	_ACK_Error	1 = slave sent $\overline{\text{ACK}}$ while the master was expecting an ACK. This may happen for example if the slave was not responding to a message.

Control Register (File Register “Bus_Control”)

The bit definitions of the control register are described in the table given below. These bits must be set by the software prior to performing certain operations. Some of the high level routines described later in this section set these bits automatically.

Bit #	Name	Description
0	_10BitAddr	1 = 10-bit slave addressing 0 = 7-bit addressing.
1	_Slave_RW	1 = READ operation 0 = WRITE operation.
2	_Last_Byte_Rcv	1 = last byte must be received. Used to send $\overline{\text{ACK}}$.
3, 4, 5	—	Unused bits, can be used as general purpose bits.
6	_SlaveActive	A status bit indicating if a slave is responding. This bit is set or cleared by calling the I2C_TEST_DEVICE macro. See description of this I2C_TEST_DEVICE macro.
7	_TIME_OUT_	A status bit indicating if a clock is stretched low for more than 1 ms, indicating a bus error. On this time out, the operation is aborted.

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Lower Level Routines

Function Name	Description
InitI2CBus_Master	Initializes Control/Status Registers, and set SDA & SCL lines. Must be called on initialization.
TxmtStartBit	Transmits a START (S) condition.
TxmtStopBit	Transmits a STOP (P) condition.
LOAD_ADDR_8	The 7-bit slave's address must be passed as a constant parameter.
LOAD_ADDR_10	The 10-bit slave's address must be passed as a constant parameter.
Txmt_Slave_Addr	Transmits a slave address. Prior to calling this routine, the address of the slave being addressed must be loaded using LOAD_ADDR_8 or LOAD_ADDR_10 routines. Also the Read/Write condition must be set in the control register.
SendData	Transmits a byte of data. Prior to calling this routine, the byte to be transmitted must be loaded into DataByte file register.
GetData	Receives a byte of data in DataByte file register. If the data byte to be received is the last byte, the _Last_Byte_Rcv bit in control register must be set prior to calling this routine.

MACROS

High Level

The high level routines are implemented as a mixture of function calls and macros. These high level routines call the low level routines described previously. In most cases only a few of the high level routines may be needed and the user can remove or not include the routines that are not necessary to conserve program memory space. Examples are given for a few functions.

I2C_TEST_DEVICE

Parameters	:	None
Purpose	:	To test if a slave is present on the network.
Description	:	Before using this macro, the address of the slave being tested must be loaded using LOAD_ADDR_8 or LOAD_ADDR_10 macro. If the slave under test is present, then “_SlaveActive” status bit (in Bus_Control file register) is set. If not, then this bit is cleared, indicating that the slave is either not present on the network or is not listening.
Message	:	S-SlAW-A-P
Example	:	<pre> LOAD_ADDR_8 0xA0 ; 24LC04 address I2C_TEST_DEVICE btfsc _SlaveActive ; See If slave is responding goto SlaveNotPresent ; 24LC04 is not present ; Slave is present ; Continue with program </pre>

I2C_WR

Parameters	:	_BYTES_, _SourcePointer_ _BYTES_ Number of bytes starting from RAM pointer _SourcePointer_ _SourcePointer_ Data Start Buffer pointer in RAM (file registers)
Purpose	:	A basic macro for writing a block of data to a slave
Description	:	This macro writes a block of data (# of bytes = _BYTES_) to a slave. The starting address of the block of data is _SourcePointer_. If an error occurs, the message is aborted and the user must check Status flags (e.g. _Txmt_Success bit)
Message	:	S-SlAW-A-D[0]-A.....A-D[N-1]-A-P
Example	:	<pre> btfsc _Bus_Busy ; Check if bus is free goto \$-1 LOAD_ADDR_8 _Slave_1_Addr I2C_WR 0x09, DataBegin ; </pre>

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I2C_WR_SUB

- Parameters : `_BYTES_`, `_SourcePointer_`, `_Sub_Address_`
`_BYTES_` Number of bytes starting from RAM pointer `_SourcePointer_`
`_SourcePointer_` Data Start Buffer pointer in RAM (file Registers)
`_Sub_Address_` Sub-address of the Slave
- Purpose : Write a block of data to a slave starting at slave's sub-addr
- Description : Same as `I2C_WR` function, except that the starting address of the slave is also specified. For example, while writing to an I²C Memory Device, the sub-addr specifies the starting address of the memory. The I²C may prove to be more efficient than this macro in most situations. Advantages will be found for Random Address Block Writes for Slaves with Auto Increment Sub-addresses (like Microchip's 24CXX series Serial EEPROMs).
- Message: `S-SlvAW-A-SubA-A-D[0]-A.....A-D[N-1]-A-P`
- Example :

```
LOAD_ADDR_8   _Slave_2_Addr           ; Load addr of 7-bit slave
I2C_WR_SUB    0x08, DataBegin+1, 0x30
```

In the above example, 8 Bytes of data starting from addr (`DataBegin+1`) is written to 24LC04 Serial EEPROM beginning at `0x30` address

I2C_WR_SUB_SWINC

- Parameters : `_BYTES_`, `_SourcePointer_`, `_Sub_Address_`
`_BYTES_` Number of bytes starting from RAM pointer `_SourcePointer_`
`_SourcePointer_` Data Start Buffer pointer in RAM (file Registers)
`_Sub_Address_` Sub-address of the Slave
- Purpose : Write a block of data to a slave starting at slave's sub-addr
- Description : Same as `I2C_WR_SUB` function, except that the sub-address (incremented) is sent after every data byte. A very inefficient message structure and the bus is given up after each data byte. This is useful for when the slave does not have an auto-increment sub-address feature.
- Message : `S-SlvAW-A-(SubA+0)-A-D[0]-A-P`
`S-SlvAW-A-(SubA+1)-A-D[1]-A-P`
and so on until #of Bytes

I2C_WR_BYTE_MEM

Parameters	:	_BYTES_, _SourcePointer_, _Sub_Address_ _BYTES_ Number of bytes starting from RAM pointer _SourcePointer_ _SourcePointer_ Data Start Buffer pointer in RAM (file Registers) _Sub_Address_ Sub-address of the Slave
Purpose	:	Write a block of data to a slave starting at slave's sub-address
Description	:	Same as I2C_WR_SUB_SWINC, except that a delay is added between each message. This is necessary for some devices, like EEPROMs, which accept only a byte at a time for programming (devices without on-chip RAM buffer) and after each byte a delay is necessary before a next byte is written.
Message	:	<i>S-SlvAW-A-(SubA+0)-A-D[0]-A-P</i> <i>Delay 1 ms</i> <i>S-SlvAW-A-(SubA+1)-A-D[1]-A-P</i> <i>Delay 1 ms</i> • • • • <i>and so on until #of Bytes</i>

I2C_WR_BUF_MEM

Parameters	:	_BYTES_, _SourcePointer_, _Sub_Address_, _Device_BUF_SIZE_ _BYTES_ Number of bytes starting from RAM pointer _SourcePointer_ _SourcePointer_ Data Start Buffer pointer in RAM (file Registers) _Sub_Address_ Sub-address of the Slave _Device_BUF_SIZE_ the slaves on-chip buffer size
Purpose	:	Write a block of data to a slave starting at slave's sub-addr
Description	:	This Macro/Function writes #of _BYTES_ to an I ² C memory device. However some devices, especially EEPROMs, must wait while the device enters into programming mode. But some devices have an on-chip temperature data hold buffer and is used to store data before the device actually enters into programming mode. For example, the 24C04 series of Serial EEPROMs from Microchip have an 8-byte data buffer. So one can send 8 bytes of data at a time and then the device enters programming mode. The master can either wait until a fixed time and then retry to program or can continuously poll for $\overline{\text{ACK}}$ bit and then transmit the next block of data for programming.
Message	:	I2C_SUB_WR operations are performed in loop and each time data buffer of BUF_SIZE is output to the device. Then the device is checked for busy and when not busy another block of data is written.

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I2C_READ

Parameters : `_BYTES_`, `_DestPointer_`
`_BYTES_` Number of bytes starting from RAM pointer `_SourcePointer_`
`_DestPointer_` Data Start Buffer pointer in RAM (file Registers)

Purpose : A basic macro for reading a block of data from a slave

Description : This macro reads a block of data (number of bytes = `_BYTES_`) from a slave. The starting address of the block of data is `_DestPointer_`. If an error occurs, the message is aborted and the user must check Status flags (e.g. `_Rcv_Success` bit). Note that on the last byte to receive, NACK is sent.

Message : S-SlVAR-A-D[0]-A-.....-A-D[N-1]-N-P

Example :

```
LOAD_ADDR_10      _Slave_3_Addr
I2C_READ_SUB      8, DataBegin
btfss              _Rcv_Success
goto               ReceiveError
goto               ReceiveSuccess
```

In the example above, 8 bytes of data is read from a 10-bit slave and stored in the master's RAM starting at address `DataBegin`.

I2C_READ_SUB

Parameters : `_BYTES_`, `_DestPointer_`, `_SubAddress`
`_BYTES_` Number of bytes starting from RAM pointer `_SourcePointer_`
`_DestPointer_` Data Start Buffer pointer in RAM (file Registers)
`_SubAddress_` Sub-address of the slave

Purpose : A basic macro for reading a block of data from a slave

Description : This macro reads a block of data (# of bytes = `_BYTES_`) from a slave starting at slave's sub-address `_SubAddress`. The data received is stored in master's RAM starting at address `_DestAddress`. If an error occurs, the message is aborted and the user must check Status flags (e.g. `_Rcv_Success` bit).

This MACRO/Subroutine reads a message from a slave device preceded by a write of the sub-address between the sub-address write and the following reads, a STOP condition is not issued and a "REPEATED START" condition is used so that another master will not take over the bus, and also that no other master will overwrite the sub-address of the same slave. This function is very commonly used in accessing Random/Sequential reads from a memory device (e.g., 24CXX serial of Serial EEPROMs from Microchip).

Message : *S-SlvAW-A-SubAddr-A-S-SlvAR-A-D[0]-A-.....-A-D[N-1]-N-P*

Example :

```
LOAD_ADDR_10  _Slave_3_Addr
I2C_READ      8,  DataBegin, 0x60
btfss        _Rcv_Success
goto         ReceiveError
goto         ReceiveSuccess
```

In the example above, 8 bytes of data is read from a 10-bit slave (starting at address 0x60h) and stored in the master's RAM starting at address `DataBegin`.

I2C_READ_BYTE or I2C_READ_STATUS

Parameters : `_DestPointer_`
`_DestPointer_` Data Start Buffer pointer in RAM (file Registers)

Purpose : To read a Status Byte from Slave

Description : Several I²C Devices can send a Status Byte upon reception of the control byte. This Macro reads a Status byte from a slave to the master's RAM location `_DestPointer_`. This function is basically the same as `I2C_READ` for a single byte read. As an example of this command, the 24Cxx serial Serial EEPROM from Microchip will send the memory data at the current location when `I2C_READ_STATUS` function is called. On successful operation of this command, W register = '1' else W register = '0' on errors.

Message : *S-SlvAR-A-D-A-N-P*

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I2C_WR_SUB_WR

Parameters	:	<code>_Bytes1_</code> , <code>_SrcPtr1_</code> , <code>_SubAddr_</code> , <code>_Bytes2_</code> , <code>_SrcPtr2_</code> <code>_Bytes1_</code> Number of bytes in the first data block <code>_SrcPtr1_</code> Starting address of first data block <code>_SubAddr_</code> Sub-address of the slave <code>_Bytes2_</code> Number of bytes in the second data block <code>_SrcPtr2_</code> Starting address of second data block
Purpose	:	To send two blocks of data to a slave at its sub address
Description	:	<p>This Macro writes two blocks of data (of variable length) starting at slave's sub-address <code>_SubAddr_</code>. This Macro is essentially the same as calling <code>I2C_WR_SUB</code> twice, but a STOP bit is not sent in-between the transmission of the two blocks. This way the Bus is not given up.</p> <p>This function may be useful for devices which need two blocks of data in which the first block may be an extended address of a slave device. For example, a large I²C memory device, or a teletext device with an extended addressing scheme, may need multiple bytes of data in the first block that represents the actual physical address and is followed by a second block that actually represents the data.</p>
Message	:	<i>S-SlvW-A-SubA-A-D1[0]-A-.....-D1[N-1]-A-D2[0]-A-.....-A-D2[M-1]-A-P</i>

I2C_WR_SUB_RD

Parameters	:	<code>_Count1_</code> , <code>_SrcPtr_</code> , <code>_SubAddr_</code> , <code>_Count2_</code> , <code>_DestPtr_</code> <code>_Count1_</code> Length of the source buffer <code>_SrcPtr_</code> Source pointer address <code>_SubAddr_</code> Sub-address of the slave <code>_Count2_</code> Length of the destination buffer <code>_DestPtr_</code> Address of destination buffer
Purpose	:	To send a block of data and then receive a block of data
Description	:	<p>This macro writes a block of data (of length <code>_Count1_</code>) to a slave starting at sub-address <code>_SubAddr_</code> and then reads a block of data (of length <code>_Count2_</code>) to the master's destination buffer (starting at address <code>_DestPtr_</code>). Although this operation can be performed using previously defined Macros, this function does not give up the bus in between the block writes and block reads. This is achieved by using the Repeated Start Condition.</p>
Message	:	<i>S-SlvW-A-SubA-A-D1[0]-A-.....-A-D1[N-1]-A-S-SlvR-A-D2[0]-A-.....-A-D2[M-1]-N-P</i>

I2C_WR_COM_WR

Parameters	:	<code>_Count1_</code> , <code>_SrcPtr1_</code> , <code>_Count2_</code> , <code>_SrcPtr2_</code>
		<code>_Count1_</code> Length of the first data block
		<code>_SrcPtr1_</code> Source pointer of the first data block
		<code>_Count2_</code> Length of the second data block
		<code>_SrcPtr2_</code> Source pointer of the second data block
Purpose	:	To send two blocks of data to a slave in one message.
Description	:	This macro writes a block of data (of length <code>_Count1_</code>) to a slave and then sends another block of data (of length <code>_Count2_</code>) without giving up the bus. For example, this kind of transaction can be used in an I ² C LCD driver where a block of control and address information is needed and then another block of actual data to be displayed is needed.
Message	:	<i>S-SlW-A-D1[0]-A-.....A-D1[N-1]-A-D2[0]-A-.....-A-D2[M-1]-A-P</i>

APPLICATIONS

The I²C Bus is a simple two wire serial protocol for inter-IC communications. Many peripheral devices (acting as slaves) are available in the market with I²C interface (e.g., serial EEPROM, clock/calendar, I/O Port expanders, LCD drivers, A/D converters). Although some of the PIC16CXXX devices do not have on-chip I²C hardware interface, due to the high speed throughput of the microcontroller (250 ns @ 16 MHz input clock), the I²C bus can be implemented using software.

Please check the Microchip BBS for the latest version of the source code. Microchip's Worldwide Web Address: www.microchip.com; Bulletin Board Support: MCHIPBBS using CompuServe® (CompuServe membership not required).

APPENDIX A: I²C_TEST.H

MPASM 01.40.01 Intermediate I2C_TEST.ASM 4-4-1997 14:47:18 PAGE 1

```

LOC  OBJECT CODE      LINE SOURCE TEXT
VALUE

00001          Title      "I2C Slave Mode Implemetation"
00002          SubTitle   "Rev 0.2          : 04 April 1997"
00003
00004
00005
00006 ;*****
00007 ;
00008 ;                I2C Slave Mode Using Software Polling
00009 ;
00010 ; Start Bit Is detected by connecting SDA to RB0/INT Pin
00011 ; Other bits, including STOP & Repeated Start Conditions are Software Polled
00012 ;
00013 ; The software is implemented using PIC16C84 & thus can be ported to all
00014 ; Enhanced core PIC16CXX products
00015 ;
00016 ;RB1 is SCL      (Any I/O Pin May Be used instead)
00017 ; RB0/INT is SDA (Must use this pin for START bit detect when in idle mode)
00018 ;
00019 ; Since Slave Mode is always Application Dependent, as a Test Program, PIC16C84 is used to
00020 ; emulate partial functionality of Microchip's 24Cxx Serial EEPROMs
00021 ;
00022 ;
00023 ; Program:          I2C_TEST.ASM
00024 ; Revision Date:   Rev 0.1          : 01 Mar 1993
00025 ;                4-04-97          Compatibility with MPASMWIN 1.40
00026 ;
00027 ;*****
00028 ;
00029 #define _MY_ADDRESS      0xD6      ; This slave's address
00030 ;
00031 #define AtoD_Slave      1
00032 #define EE_Slave        0
00033
00034 ;

```

```

00035
00036          LIST      p = 16C71
00037          ERRORLEVEL - 302
00038
00039          Radix      DEC
00040          EXPAND
00041
00F42400      00042 _ClkIn      equ      16000000
003D0900      00043 _ClkOut      equ      (_ClkIn >> 2)
00044 ;
00045 ;
00000020      00046 ControlByte EQU      0x20
00047 #define      _STOP ControlByte, 0
00048 #define      _START ControlByte, 1
00049 #define      _RW      ControlByte, 2
00050 #define      _ACK      ControlByte, 3
00000021      00051 SlvStatus EQU      0x21
00052 ;
00053 ;
00054
00055          include    "p16c71.inc"
00001          LIST
00002 ; P16C71.INC Standard Header File, Version 1.00      Microchip Technology, Inc.
00142          LIST
00056
00000008      00057 _eedata set      0x08
00000009      00058 _eeadr set      0x09
00059
00000008      00060 _eecon1 set      0x08
00000009      00061 _eecon2 set      0x09          ; bank 1
00062
00063 #define      _rd      _eecon1,0
00064 #define      _wr      _eecon1,1
00065 #define      _wren    _eecon1,2
00066 #define      _wrerr   _eecon1,3
00067 #define      _eeif    _eecon1,4
00068
00000000      00069 LSB      equ      0
00000007      00070 MSB      equ      7
00071
00072          include    "i2c.h"
00001 ;*****
*
00002 ;          I2C Bus Header File
00003 ;*****
*
00004

```

```

003D0900      00005  _ClkOut          equ      (_ClkIn >> 2)
00006
00007 ;
00008 ; Compute the delay constants for setup & hold times
00009 ;
00000010      00010  _40uS_Delay      set      (_ClkOut/250000)
00000012      00011  _47uS_Delay      set      (_ClkOut/212766)
00000014      00012  _50uS_Delay      set      (_ClkOut/200000)
00013
00014 #define _OPTION_INIT      (0xC0 | 0x03)          ; Prescaler to TMR0 for Appox 1 mSec timeout
00015 ;
00016 #define _SCL      PORTB,0
00017 #define _SDA      PORTB,1
00018
00019 #define _SCL_TRIS      _trisb,0
00020 #define _SDA_TRIS      _trisb,1
00021
00022 #define _WRITE_      0
00023 #define _READ_      1
00024
00025
00026 ;                      Register File Variables
00027
00028
00029          CBLOCK      0x0C
0000000C      00030          SlaveAddr          ; Slave Addr must be loaded into this reg
0000000D      00031          SlaveAddrHi        ; for 10 bit addressing mode
0000000E      00032          DataByte          ; load this reg with the data to be transmitted
0000000F      00033          BitCount          ; The bit number (0:7) transmitted or received
00000010      00034          Bus_Status          ; Status Reg of I2C Bus for both TXMT & RCVE
00000011      00035          Bus_Control        ; control Register of I2C Bus
00000012      00036          DelayCount
00000013      00037          DataByteCopy        ; copy of DataByte for Left Shifts (destructive)
00038
00000014      00039          SubAddr          ; sub-address of slave (used in I2C_HIGH.ASM)
00000015      00040          SrcPtr          ; source pointer for data to be transmitted
00041
00000016      00042          tempCount          ; a temp variable for scratch RAM
00000017      00043          StoreTemp_1        ; a temp variable for scratch RAM, do not disturb contents
00044
00000018      00045          _End_I2C_Ram          ; unused, only for ref of end of RAM allocation
00046          ENDC
00047
00048 ;*****
00049 ;                      I2C Bus Status Reg Bit Definitions
00050 ;*****
00051

```

```

00052 #define _Bus_Busy      Bus_Status,0
00053 #define _Abort        Bus_Status,1
00054 #define _Txmt_Progress Bus_Status,2
00055 #define _Rcv_Progress  Bus_Status,3
00056
00057 #define _Txmt_Success    Bus_Status,4
00058 #define _Rcv_Success    Bus_Status,5
00059 #define _Fatal_Error    Bus_Status,6
00060 #define _ACK_Error       Bus_Status,7
00061
00062 ;*****
00063 ;                               I2C Bus Control Register
00064 ;*****
00065 #define _10BitAddr        Bus_Control,0
00066 #define _Slave_RW        Bus_Control,1
00067 #define _Last_Byte_Rcv   Bus_Control,2
00068
00069 #define _SlaveActive      Bus_Control,6
00070 #define _TIME_OUT_       Bus_Control,7
00071
00072
00073
00074
00075 ;*****
*
00076 ;                               General Purpose Macros
00077 ;*****
*
00078
00079 RELEASE_BUS      MACRO
00080                 bsf      STATUS,RP0      ; select Bank1
00081                 bsf      _SDA           ; tristate SDA
00082                 bsf      _SCL           ; tristate SCL
00083 ;                 bcf      _Bus_Busy     ; Bus Not Busy, TEMP ????, set/clear on Start & Stop
00084                 ENDM
00085
00086 ;*****
*
00087 ;                               A MACRO To Load 8 OR 10 Bit Address To The Address Registers
00088 ;
00089 ; SLAVE_ADDRESS is a constant and is loaded into the SlaveAddress Register(s) depending
00090 ; on 8 or 10 bit addressing modes
00091 ;*****
*
00092
00093 LOAD_ADDR_10     MACRO  SLAVE_ADDRESS
00094

```

```

00095          bsf      _10BitAddr          ; Slave has 10 bit address
00096          movlw   (SLAVE_ADDRESS & 0xff)
00097          movwf   SlaveAddr          ; load low byte of address
00098          movlw   (((SLAVE_ADDRESS >> 7) & 0x06) | 0xF0) ; 10 bit addr is 11110XX0
00099          movwf   SlaveAddr+1        ; hi order address
00100
00101          ENDM
00102
00103 LOAD_ADDR_8  MACRO   SLAVE_ADDRESS
00104
00105          bcf      _10BitAddr          ; Set for 8 Bit Address Mode
00106          movlw   (SLAVE_ADDRESS & 0xff)
00107          movwf   SlaveAddr
00108
00109          ENDM
00073
00074
00075          CBLOCK  _End_I2C_Ram
00076          SaveStatus          ; copy Of STATUS Reg
00077          SaveW register        ; copy of W register
00078          byteCount
00079          HoldData
00080          ENDC
00081
00082          CBLOCK  0x20
00083          DataBegin          ; Data to be read or written is stored here
00084          ENDC
00085
00086 ;*****
00087
00088          ORG      0x00
00089
00090          goto    Start
00091 ;
00092          ORG      0x04
00093 ;*****
00094 ;
00095 ;
00096 ;   For I2C Slave routines, only Rb0/INT interrupt is used for START Bit Detect From
00097 ;   Idle Mode
00098 ;
00099 ;*****
00100
00101 Interrupt:
00102 ;
00103 ;   At first check if START Bit Detect (currently only INT pin interrupt is enabled, if other
00104 ;   Interrupts are enabled, then check for other interrupts)

```



```

0004 1C8B      00105 ;
0005 0009      00106      btfss  INTCON,INTF
0005 0009      00107      retfie          ; other interrupt, simply return & enable GIE
0005 0009      00108 ;
0005 0009      00109 ; Save Status
0005 0009      00110 ;
0006 0099      00111      movwf  SaveW register
0007 0E03      00112      swapf  STATUS,W          ; affects no STATUS bits : Only way OUT to save STATUS Reg ?????
0008 0098      00113      movwf  SaveStatus
0008 0098      00114 ;
0009 1283      00115      bcf    STATUS,RP0
000A 1C06      00116      btfss  _SCL          ; Most likely a START Bit, Hold Time of START Bit must be valid from an INT to here
000B 280F      00117      goto   RestoreStatus ; Not a Valid START Bit
000C 1886      00118      btfsc  _SDA          ; If a valid Falling Edge on SDA when SCL is high, SDA must now be Low
000D 280F      00119      goto   RestoreStatus ; Not a Valid START Bit
000E 282A      00120      goto   StartBitDetect ; A Valid Start Bit Is Detected, process & then Branch to "Restore Status"
000E 282A      00121 ;
000E 282A      00122 ; Restore Status
000E 282A      00123 ;
000F           00124 RestoreStatus:
000F           00125
000F 0E18      00126      swapf  SaveStatus,W
0010 0083      00127      movwf  STATUS          ; restore STATUS Reg
0011 0E99      00128      swapf  SaveW register, F ; save W register
0012 0E19      00129      swapf  SaveW register,W ; restore W register
0012 0E19      00130 ;
0013 108B      00131      bcf    INTCON,INTF
0014 0009      00132      retfie
0014 0009      00133 ;
0014 0009      00134
0014 0009      00135 ;*****
0014 0009      00136 ;
0014 0009      00137 ;*****
0014 0009      00138
0015           00139 Start:
0015           00140
0015 2019      00141      call   Init_I2C_Slave ; Initialize I2C Bus for Slave Mode, wait for START Bit detect
0015 2019      00142 ;
0016 178B      00143      bsf    INTCON,GIE      ; Enable Interrupts
0017           00144 wait:
0017 0064      00145      clrwdt ; User can write code here, will be interrupted by Falling Edge on INT
0018 2817      00146      goto   wait           ; Loop until Start Bit Detect
0018 2817      00147
0018 2817      00148
0018 2817      00149 ;
0018 2817      00150 ;*****
0018 2817      00151 ;

```

```

0019          00152
0019          00153 Init_I2C_Slave:
0019          00154
0019 01A0      00155          clrf   ControlByte
001A 1683      00156          bsf    STATUS,RP0
001B 30C3      00157          movlw  _OPTION_INIT
001C 0081      00158          movwf  OPTION_REG      ; initially set INT for Falling Edge INT
001D 1406      00159          bsf    _SCL
001E 1486      00160          bsf    _SDA          ; set TRIS of SCL & SDA to inputs, pulled up by external resistors
001F          00161
001F 1283      00162          bcf    STATUS,RP0
0020 0806      00163          movf   PORTB,W
0021 39FC      00164          andlw  0xFC          ; do not use BSF & BCF on Port Pins
0022 0086      00165          movwf  PORTB          ; set SDA & SCL to zero. From Now on, simply play with tris
0023          00166
0023 0194      00167          clrf   SubAddr      ; Set Sub Address to Zero
0023          00168 ;
0023          00169 ; Initialize A/D Setup or EEPROM Control Regs
0023          00170 ;
0023          00171
0023          00172 ;#if AtoD_Slave
0023          00173 ;          movlw  0x01          ; Select Channel 0, and turn on A/D Module with Fosc/2 Sampling Rate
0023          00174 ;          movwf  _adcon0      ; already in Bank0, STATUS,RP0 = 0
0023          00175 ;          bsf    STATUS,RP0
0023          00176 ;          clrf   _adcon1      ; 4 analog channels with internal Vref
0023          00177 ;#else
0024 0189      00178          clrf   _eeadr      ; already in Bank0, init EEPROM Addr = 0
0025 1683      00179          bsf    STATUS,RP0
0026 0188      00180          clrf   _eecon1     ; clear err flag
0026          00181 ;#endif
0026          00182 ;
0027 018B      00183          clrf   INTCON
0028 160B      00184          bsf    INTCON,INTE  ; Enable Falling Edge Interrupt On SDA (connected on RB0/INT pin)
0029 0008      00185          return
0029          00186
0029          00187 ;
0029          00188 ;*****
0029          00189 ;          In-Line Code For I2C-Slave
0029          00190 ; Returns to detect next Start Bit after a STOP Bit Is Detected
0029          00191 ; This implementation is very in-efficient if the Master is constantly sending a Repeated START Condition
0029          00192 ;
0029          00193 ;*****
0029          00194
002A          00195 StartBitDetect:
002A 2045      00196          call   RcvByte      ; 1st byte received in DataByte
002B 0064      00197          clrwdt
002C 1820      00198          btfsc  _STOP

```

```

002D 283F      00199          goto    i2c_start_wait ; STOP bit Detected, wait for another START
002E 18A0      00200          btfsc   _START
002F 282A      00201          goto    StartBitDetect ; a Repeated START condition
00202 ;
00203 ; The received byte in DataByte contains R/W & 7 Address the address
00204 ; If address match send ACK bit else NACK
00205 ;
0030 1120      00206          bcf     _RW
0031 180E      00207          btfsc   DataByte,LSB
0032 1520      00208          bsf     _RW ; LSB of the 1st byte received contains R/W info
0033 100E      00209          bcf     DataByte,LSB
00210 ;
0034 080E      00211          movf    DataByte,W
0035 3AD6      00212          xorlw   _MY_ADDRESS ; if match, then Z bit is set
0036 1D03      00213          btfss  STATUS,Z
0037 283D      00214          goto    SendNACK ; No Address Match, NACK
00215 ;
00216 ; Address Match Occured, send ACK
00217 ;
0038 1403      00218          bsf     STATUS,C ; SendAck routine sends ACK if Carry == 1
0039 20B3      00219          call   SendAck
003A 1920      00220          btfsc  _RW
003B 287B      00221          goto    SendReqData ; read operation, so send current Data
003C 2867      00222          goto    RcvReqData ; receive 2 bytes of data, sub-addr & data byte
00223 ;
00224 ;*****
00225 ;
003D          00226 SendNACK:
003D 1003      00227          bcf     STATUS,C ; SendAck routine sends NACK if Carry == 0
003E 20B3      00228          call   SendAck ; address not us, so wait for another start bit
00229 ;
003F          00230 i2c_start_wait:
003F 0064      00231          clrwdt
0040 1683      00232          bsf     STATUS,RP0
0041 108B      00233          bcf     INTCON,INTF
0042 1406      00234          bsf     _SCL ; release CLK line, may be held in low by us
0043 1486      00235          bsf     _SDA ; release SDA
0044 280F      00236          goto   RestoreStatus
00237 ;
00238 ;*****
00239 ;
00240 ;*****
00241 ;
0045          00242 RcvByte:
0045 01A1      00243          clrf   SlvStatus
00244 ;
0046 3008      00245          movlw  0x08

```

```

0047 008F      00246      movwf    BitCount
                00247 ;
0048 1283      00248      bcf     STATUS,RP0
0049 1806      00249      btfsz  _SCL
004A 2849      00250      goto   $-1      ; wait until SCL is low and then Read the Control Byte
                00251 ;
004B 1683      00252      bsf     STATUS,RP0
004C 1406      00253      bsf     _SCL      ; release CLK, possibly held low
004D 1283      00254      bcf     STATUS,RP0
                00255 ;
004E          00256 RcvNextBit:
004E 1C06      00257      btfsz  _SCL
004F 284E      00258      goto   $-1      ; wait until clock is high, for valid data
0050 1886      00259      btfsz  _SDA
0051 285A      00260      goto   Rcvd_1
0052          00261 Rcvd_0:
0052 1003      00262      bcf     STATUS,C
0053 0D8E      00263      rlf    DataByte, F      ; left shift data ( MSB first)
0054          00264 _WaitClkLo1:
0054 1C06      00265      btfsz  _SCL
0055 2862      00266      goto   next1
0056 1C86      00267      btfsz  _SDA      ; SDA must still be low when CLK is high, else may be a STOP
0057 2854      00268      goto   _WaitClkLo1
0058 1420      00269      bsf    _STOP
0059 0008      00270      return
                00271 ;
005A          00272 Rcvd_1:
005A 1403      00273      bsf    STATUS,C
005B 0D8E      00274      rlf    DataByte, F
005C          00275 _WaitClkLo2:
005C 1C06      00276      btfsz  _SCL
005D 2862      00277      goto   next1      ; CLK went low, process next bit
005E 1886      00278      btfsz  _SDA      ; SDA must still be high when CLK is high, else may be a Repeated START
005F 285C      00279      goto   _WaitClkLo2
0060 14A0      00280      bsf    _START
0061 0008      00281      return
                00282 ;
0062          00283 next1:
0062 0B8F      00284      decfsz BitCount, F
0063 284E      00285      goto   RcvNextBit
                00286 ;
                00287 ; A complete Byte Received, HOLD Master's Clock Line Low to force a wait state
                00288 ;
0064 1683      00289      bsf    STATUS,RP0
0065 1006      00290      bcf    _SCL      ; force SCL Low for wait state
0066 0008      00291      return
                00292 ;*****

```

```

00293 ;                               Write Operation Requested
00294 ;
00295 ; Read Sub Address and A Data Byte & Acknowledge, if no errors
00296 ; Currently Only One Byte Is Programmed At A Time, Buffering scheme is unimplemented
00297 ;
00298 ;*****
00299
0067      00300 RcvReqData
0067 2045      00301      call    RcvByte      ; Sub-Address Byte Received in DataByte, store in Sub-Addr
0068 080E      00302      movf    DataByte,W
0069 0094      00303      movwf   SubAddr
006A 0064      00304      clrwdt
006B 1820      00305      btfsc  _STOP
006C 283F      00306      goto   i2c_start_wait ; STOP bit Detected, wait for another START
006D 18A0      00307      btfsc  _START
006E 282A      00308      goto   StartBitDetect ; a Repeated START condition
006F 1403      00309      bsf    STATUS,C      ; SendAck routine sends ACK if Carry == 1
0070 20B3      00310      call   SendAck       ; Sub-Addr Received, Send an ACK
00311 ;
00312 ; Receive Data Byte to Write To EEPROM
00313 ;
0071 2045      00314      call   RcvByte       ; Sub-Address Byte Received in DataByte, store in Sub-Addr
0072 0064      00315      clrwdt
0073 1820      00316      btfsc  _STOP
0074 283F      00317      goto   i2c_start_wait ; STOP bit Detected, wait for another START
0075 18A0      00318      btfsc  _START
0076 282A      00319      goto   StartBitDetect ; a Repeated START condition
0077 1403      00320      bsf    STATUS,C      ; SendAck routine sends ACK if Carry == 1
0078 20B3      00321      call   SendAck       ; Sub-Addr Received, Send an ACK
0079 20CD      00322      call   EEpromWrite   ; Program EEPROM
007A 280F      00323      goto   RestoreStatus ; STOP bit Detected, wait for another START
00324
00325 ;*****
00326 ;                               Read Operation Requested
00327 ;
00328 ; Send A/D Data Of Required Channel until NACK By Master
00329 ;
00330 ;*****
00331
007B      00332 SendReqData:
00333
007B 1283      00334      bcf    STATUS,RP0
007C 0814      00335      movf   SubAddr,W
007D 0089      00336      movwf  _eaddr        ; Load Sub_Addr Of EEPROM
00337
00338 ;
007E      00339 SendNextByte:

```

```

007E 1683      00340      bsf     STATUS,RP0
007F 1408      00341      bsf     _rd                ; read EEPROM
0080 1283      00342      bcf     STATUS,RP0
0081 0808      00343      movf    _eedata,W
0082 008E      00344      movwf   DataByte          ; DataByte = EEPROM(addr)
0083 0A89      00345      incf    _eeadr, F         ; auto-increment sub-address
                                00346
0084 208D      00347      call    TxmtByte          ; send out EEPROM Data
0085 0064      00348      clrwdt
0086 18A0      00349      btfsc   _START           ; check for abnormal START
0087 283F      00350      goto    i2c_start_wait
0088 20C0      00351      call    ReadACK
0089 0064      00352      clrwdt
008A 1DA0      00353      btfss   _ACK             ; _ACK == 1 if +ve ACK Rcvd
008B 283F      00354      goto    i2c_start_wait   ; NACK Received, a START or STOP condition may occur
008C 287E      00355      goto    SendNextByte     ; continue to send until NACK
                                00356 ;
00357 ;*****
00358
008D          00359 TxmtByte:
008D 080E      00360      movf    DataByte,W
008E 0093      00361      movwf   DataByteCopy     ; make copy of DataByte
008F 3008      00362      movlw   0x08
0090 008F      00363      movwf   BitCount
0091 01A1      00364      clrf    SlvStatus
                                00365 ;
0092          00366 TxmtNextBit:
0092 1683      00367      bsf     STATUS,RP0
0093 0D93      00368      rlf     DataByteCopy, F  ; MSB First
                                00369
0094 1803      00370      btfsc   STATUS,C
0095 28A1      00371      goto    Txmt_1
0096          00372 Txmt_0
0096 1086      00373      bcf     _SDA
0097 0000      00374      nop
0098 1406      00375      bsf     _SCL             ; release clock line, let master pull it high
0099 1283      00376      bcf     STATUS,RP0
009A 1C06      00377      btfss   _SCL
009B 289A      00378      goto    $-1             ; wait until clk goes high
009C 1806      00379      btfsc   _SCL
009D 289C      00380      goto    $-1             ; wait until clk goes low
009E 1683      00381      bsf     STATUS,RP0
009F 1006      00382      bcf     _SCL             ; clk went low, continue to hold it low
00A0 28AD      00383      goto    Q_TxmtNextBit
                                00384
                                00385
00A1          00386 Txmt_1

```

```

00A1 1486      00387      bsf      _SDA
00A2 0000      00388      nop
00A3 1406      00389      bsf      _SCL      ; release clock line, let master pull it high
00A4 1283      00390      bcf      STATUS,RP0
00A5 1C06      00391      btfss    _SCL
00A6 28A5      00392      goto     $-1      ; wait until clk goes high
00A7           00393      _IsClkLo_1
00A7 1C86      00394      btfss    _SDA
00A8 28B1      00395      goto     MaybeErr_Txmt ; must never come here, illegal Repeated Start
00A9 1806      00396      btfsc    _SCL
00AA 28A7      00397      goto     _IsClkLo_1 ; wait until clk goes low
00AB 1683      00398
00AC 1006      00399      bsf      STATUS,RP0
00AC 1006      00400      bcf      _SCL      ; clk went low, continue to hold it low
00AD           00401      ;
00AD           00402      Q_TxmtNextBit
00AD 0B8F      00403      decfsz   BitCount, F
00AE 2892      00404      goto     TxmtNextBit
00AF 1486      00405      bsf      _SDA      ; release SDA for Master's ACK
00B0 0008      00406      return
00B0           00407      ;
00B1           00408      MaybeErr_Txmt:
00B1 14A0      00409      bsf      _START    ; illegal Repeated START condition during a byte transfer
00B2 0008      00410      return
00B2           00411      ;
00B2           00412      ;*****
00B2           00413      ;                      Send ACK/NACK to Master
00B2           00414      ;
00B2           00415      ; Prior to calling this routine, set CARRY bit to 1 for sending +ve ACK & set CARRY = 0, for NACK
00B2           00416      ;
00B2           00417      ;*****
00B2           00418
00B3           00419      SendAck:
00B3 1683      00420      bsf      STATUS,RP0
00B4 1803      00421      btfsc    STATUS,C    ; Carry bit == 1 for ACK else NACK
00B5 1086      00422      bcf      _SDA      ; pull SDA low to send +ve ACK
00B6 1406      00423      bsf      _SCL      ; release CLK line, let master clk it
00B7 1283      00424      bcf      STATUS,RP0
00B8 1C06      00425      btfss    _SCL
00B9 28B8      00426      goto     $-1      ; loop until Clk High
00BA 1806      00427      btfsc    _SCL
00BB 28BA      00428      goto     $-1      ; loop until Clk is Low, ACK bit sent
00BC 1683      00429      bsf      STATUS,RP0
00BD 1006      00430      bcf      _SCL      ; HOLD CLK Line LOW
00BE 1486      00431      bsf      _SDA      ; ACK over, release SDA line for Master control
00BE           00432      ;
00BE           00433      ;

```

```

00BF 0008      00434          return
                00435 ;
                00436 ;*****
                00437 ;                               Read ACK Sent By Master
                00438 ;
                00439 ; If +ve ACK then set _ACK bit in SlaveStatus Reg, else 0
                00440 ;
                00441 ;*****
                00442
00C0           00443 ReadACK:
00C0 1683      00444          bsf     STATUS,RP0
00C1 1406      00445          bsf     _SCL           ; release clock
00C2 1283      00446          bcf     STATUS,RP0
00C3 1C06      00447          btfss  _SCL
00C4 28C3      00448          goto   $-1           ; wait until clock is high (9 the bit:ACK)
00C5 15A0      00449          bsf     _ACK           ; expecting a +ve ACK
00C6 1886      00450          btfsc  _SDA
00C7 11A0      00451          bcf     _ACK           ; NACK rcvd, stop transmission
00C8 1806      00452          btfsc  _SCL
00C9 28C8      00453          goto   $-1           ; wait until Clock is low
00CA 1683      00454          bsf     STATUS,RP0
00CB 1006      00455          bcf     _SCL           ; force Clock low
00CC 0008      00456          return
                00457 ;*****
                00458 ;                               Write One Byte Of Data To EEPROM Array at Sub-Addr
                00459 ;
                00460 ;*****
00CD           00461 EEpromWrite:
00CD 1283      00462          bcf     STATUS,RP0
00CE 0814      00463          movf   SubAddr,W
00CF 0089      00464          movwf  _eeadr         ; load sub-address
00D0 080E      00465          movf   DataByte,W
00D1 0088      00466          movwf  _eedata       ; load data to be written into EEDATA
00D2 1683      00467          bsf     STATUS,RP0
00D3 1508      00468          bsf     _wren        ; enable write operation
00D4 1188      00469          bcf     _wrerr       ; clear any previous error flags
00D5 3055      00470          movlw  0x55
00D6 0089      00471          movwf  _eecon2
00D7 30AA      00472          movlw  0xAA
00D8 0089      00473          movwf  _eecon2
00D9 1488      00474          bsf     _wr          ; start Write Operation
                00475 ;
00DA 1406      00476          bsf     _SCL         ; release CLK line, may be held in low by us
00DB 1486      00477          bsf     _SDA         ; release SDA
                00478 ;
00DC 0064      00479          clrwdt
00DD 1888      00480          btfsc  _wr          ; Poll until WR Over

```



```

00DE 28DC          00481          goto    $-2
                  00482 ;
00DF 1108          00483          bcf     _wren      ; disable write operations
00E0 0064          00484          clrwdt
00E1 108B          00485          bcf     INTCON,INTF
                  00486 ;
00E2 0008          00487          return
                  00488 ;*****
                  00489
                  00490
                  00491          end

```

MEMORY USAGE MAP ('X' = Used, '-' = Unused)

```

0000 : X--XXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
0040 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
0080 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
00C0 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXX-----

```

All other memory blocks unused.

Program Memory Words Used: 224
Program Memory Words Free: 800

Errors : 0
Warnings : 0 reported, 0 suppressed
Messages : 0 reported, 1 suppressed

Please check the Microchip BBS for the latest version of the source code. Microchip's Worldwide Web Address: www.microchip.com; Bulletin Board Support: MCHIPBBS using CompuServe® (CompuServe membership not required).

APPENDIX B: TEST.ASM

MPASM 01.40.01 Intermediate I2CTEST.ASM 4-4-1997 14:45:51 PAGE 1

```

LOC  OBJECT CODE      LINE SOURCE TEXT
VALUE

00001          Title          "I2C Master Mode Implemetation"
00002          SubTitle       "Rev 0.2          : 04 April 1997"
00003
00004 ;*****
00005 ;
00006          Software Implementation Of I2C Master Mode
00007 ;
00008 ;          * Master Transmitter & Master Receiver Implemented in software
00009 ;          * Slave Mode implemented in hardware
00010 ;
00011 ;          *          Refer to Signetics/Philips I2C-Bus Specification
00012 ;
00013 ;          The software is implemented using PIC16C71 & thus can be ported to all Enhanced core PIC16CXX product
00014 ;
00015 ;          RB1 is SDA          (Any I/O Pin May Be used instead)
00016 ;          RB0/INT is SCL     (Any I/O Pin May Be used instead)
00017 ;
00018 ;
00019 ;          Program:          I2CTEST.ASM
00020 ;          Revision Date:    Rev 0.1          : 01 Mar 1993
00021 ;          4-04-97          Compatibility with MPASMWIN 1.40
00022 ;
00023 ;*****
00024
00025          LIST      p = 16C71
00026          ERRORLEVEL -302
00027          Radix     DEC
00028
00F42400      00029 _ClkIn      equ      16000000          ; Input Clock Frequency Of PIC16C71
00030
00031          include     <p16c71.inc>
00001          LIST
00002 ; P16C71.INC Standard Header File, Version 1.00      Microchip Technology, Inc.
00142          LIST

```

```

00000001      00032
00000000      00033 TRUE   equ    1
00000000      00034 FALSE  equ    0
00000000      00035
00000000      00036 LSB    equ    0
00000007      00037 MSB    equ    7
00038
00039 ;
00040 #define _Slave_1_Addr  0xA0          ; Serial EEPROM #1
00041 #define _Slave_2_Addr  0xAC          ; Serial EEPROM #2
00042 #define _Slave_3_Addr  0xD6          ; Slave PIC16CXX
00043
00044 #define _ENABLE_BUS_FREE_TIME  TRUE
00045 #define _CLOCK_STRETCH_CHECK  TRUE
00046 #define _INCLUDE_HIGH_LEVEL_I2C TRUE
00047
00048
00049          include      "i2c.h"
00001 ;*****
00002 ;                      I2C Bus Header File
00003 ;*****
00004
003D0900      00005 _ClkOut      equ    (_ClkIn >> 2)
00006
00007 ;
00008 ; Compute the delay constants for setup & hold times
00009 ;
00000010      00010 _40uS_Delay   set    (_ClkOut/250000)
00000012      00011 _47uS_Delay   set    (_ClkOut/212766)
00000014      00012 _50uS_Delay   set    (_ClkOut/200000)
00013
00014 #define _OPTION_INIT    (0xC0 | 0x03) ; Prescaler to TMR0 for Appox 1 mSec timeout
00015 ;
00016 #define _SCL            PORTB,0
00017 #define _SDA            PORTB,1
00018
00019 #define _SCL_TRIS       _trisb,0
00020 #define _SDA_TRIS       _trisb,1
00021
00022 #define _WRITE_         0
00023 #define _READ_          1
00024
00025
00026          ; Register File Variables
00027
00028
00029          CBLOCK 0x0C

```

```

0000000C      00030      SlaveAddr          ; Slave Addr must be loaded into this reg
0000000D      00031      SlaveAddrHi        ; for 10 bit addressing mode
0000000E      00032      DataByte          ; load this reg with the data to be transmitted
0000000F      00033      BitCount         ; The bit number (0:7) transmitted or received
00000010      00034      Bus_Status       ; Status Reg of I2C Bus for both TXMT & RCVE
00000011      00035      Bus_Control     ; control Register of I2C Bus
00000012      00036      DelayCount      ;
00000013      00037      DataByteCopy     ; copy of DataByte for Left Shifts (destructive)
00000014      00038
00000014      00039      SubAddr          ; sub-address of slave (used in I2C_HIGH.ASM)
00000015      00040      SrcPtr           ; source pointer for data to be transmitted
00000015      00041
00000016      00042      tempCount      ; a temp variable for scratch RAM
00000017      00043      StoreTemp_1     ; a temp variable for scratch RAM, do not disturb contents
00000017      00044
00000018      00045      _End_I2C_Ram    ; unused, only for ref of end of RAM allocation
00000018      00046      ENDC
00000018      00047
000048 ;*****
000049 ;           I2C Bus Status Reg Bit Definitions
000050 ;*****
000051
000052 #define _Bus_Busy      Bus_Status,0
000053 #define _Abort        Bus_Status,1
000054 #define _Txmt_Progress Bus_Status,2
000055 #define _Rcv_Progress Bus_Status,3
000056
000057 #define _Txmt_Success  Bus_Status,4
000058 #define _Rcv_Success  Bus_Status,5
000059 #define _Fatal_Error   Bus_Status,6
000060 #define _ACK_Error     Bus_Status,7
000061
000062 ;*****
000063 ;           I2C Bus Contro Register
000064 ;*****
000065 #define _10BitAddr     Bus_Control,0
000066 #define _Slave_RW     Bus_Control,1
000067 #define _Last_Byte_Rcv Bus_Control,2
000068
000069 #define _SlaveActive   Bus_Control,6
000070 #define _TIME_OUT_    Bus_Control,7
000071
000072
000073
000074
000075 ;*****
000076 ;           General Purpose Macros

```

```

00077 ;*****
00078
00079 RELEASE_BUS    MACRO
00080                 bsf     STATUS,RP0      ; select Bank1
00081                 bsf     _SDA           ; tristate SDA
00082                 bsf     _SCL         ; tristate SCL
00083 ;                 bcf     _Bus_Busy    ; Bus Not Busy, TEMP ????, set/clear on Start & Stop
00084                 ENDM
00085
00086 ;*****
00087 ;                 A MACRO To Load 8 OR 10 Bit Address To The Address Registers
00088 ;
00089 ; SLAVE_ADDRESS is a constant and is loaded into the SlaveAddress Register(s) depending
00090 ; on 8 or 10 bit addressing modes
00091 ;*****
00092
00093 LOAD_ADDR_10    MACRO  SLAVE_ADDRESS
00094
00095                 bsf     _10BitAddr    ; Slave has 10 bit address
00096                 movlw  (SLAVE_ADDRESS & 0xff)
00097                 movwf  SlaveAddr      ; load low byte of address
00098                 movlw  (((SLAVE_ADDRESS >> 7) & 0x06) | 0xF0) ; 10 bit addr is 11110XX0
00099                 movwf  SlaveAddr+1   ; hi order address
00100
00101                 ENDM
00102
00103 LOAD_ADDR_8     MACRO  SLAVE_ADDRESS
00104
00105                 bcf     _10BitAddr    ; Set for 8 Bit Address Mode
00106                 movlw  (SLAVE_ADDRESS & 0xff)
00107                 movwf  SlaveAddr
00108
00109                 ENDM
00110
00050
00051                 CBLOCK  _End_I2C_Ram
00052                 SaveStatus           ; copy of STATUS Reg
00053                 SaveW register      ; copy of W register
00054                 byteCount
00055                 HoldData
00056                 ENDC
00057
00058                 CBLOCK  0x20
00059                 DataBegin           ; Data to be read or written is stored here
00060                 ENDC
00061
00062
00000018
00000019
0000001A
0000001B
00000020
0000
00063                 ORG     0x00

```

```

00064
0000 2956      00065          goto    Start
00066 ;
0004          00067          ORG     0x04
00068 ;*****
00069 ;                      Interrupt Service Routine
00070 ;
00071 ;   For I2C routines, only TMR0 interrupt is used
00072 ; TMR0 Interrupts enabled only if Clock Stretching is Used
00073 ; On TMR0 timeout interrupt, disable TMR0 Interrupt, clear pending flags,
00074 ; MUST set _TIME_OUT_ flag saying possibly a FATAL error occurred
00075 ; The user may choose to retry the operation again later
00076 ;
00077 ;*****
00078
0004          00079 Interrupt:
00080 ;
00081 ; Save Interrupt Status (W register & STATUS regs)
00082 ;
0004 0099      00083      movwf   SaveW register      ; Save W register
0005 0E03      00084      swapf   STATUS,W          ; affects no STATUS bits : Only way OUT to save STATUS Reg ?????
0006 0098      00085      movwf   SaveStatus      ; Save STATUS Reg
0007 1D0B      00086      if _CLOCK_STRETCH_CHECK      ; TMR0 Interrupts enabled only if Clock Stretching is Used
0008 280B      00087      btfss   INTCON,T0IF
0009 1791      00088      goto    MaybeOtherInt      ; other Interrupts
000A 110B      00089      bsf     _TIME_OUT_      ; MUST set this Flag, can take other desired actions here
00090      00090      bcf     INTCON,T0IF
00091      endif
00092 ;
00093 ; Check For Other Interrupts Here, This program usesd only TMR0 & INT Interrupt
00094 ;
000B          00095 MayBeOtherInt:
000B 0000      00096      NOP
00097 ;
000C          00098 RestoreIntStatus:          ; Restore Interrupt Status
000C 0E18      00099      swapf   SaveStatus,W
000D 0083      00100      movwf   STATUS          ; restore STATUS Reg
000E 0E99      00101      swapf   SaveW register, F
000F 0E19      00102      swapf   SaveW register,W      ; restore W register
0010 0009      00103      retfie
00104 ;
00105 ;*****
00106 ;                      Include I2C High Level & Low Level Routines
00107      if _INCLUDE_HIGH_LEVEL_I2C
00108          include    "i2c_high.inc"
00001 ;*****
00002 ;

```

```

00003 ;                               I2C Master : General Purpose Macros & Subroutines
00004 ;
00005 ;                               High Level Routines, Uses Low level Routines (in I2C_LOW.ASM)
00006 ;
00007 ;
00008 ;           Program:           I2C_HIGH.ASM
00009 ;           Revision Date:
00010 ;                               1-16-97           Compatibility with MPASMWIN 1.40
00011 ;
00012 ;*****
00013 ;
00014 ;
00015 ;*****
00016 ;
00017 ;                               I2C_TEST_DEVICE
00018 ; MACRO
00019 ;
00020 ;   If Slave Device is listening, then _SlaveActive bit is set, else is cleared
00021 ;
00022 ;           Parameter : NONE
00023 ;
00024 ;   Sequence Of Operations :
00025 ;           S-SlvAW-A-P
00026 ;   If A is +ve device is listening, else either busy, not present or error condition
00027 ;
00028 ;   This test may also be used to check for eample if a Serial EEPROM is in internal programming
00029 ;   mode
00030 ;
00031 ;   NOTE : The address of the slave must be loaded into SlaveAddress Registers, and 10 or 8 bit
00032 ;           mode addressing must be set
00033 ;*****
00034 ;
00035 I2C_TEST_DEVICE           MACRO
00036 ;
00037 ;           call   IsSlaveActive           ; TEMP ???? : Assembler Error with this MACRO
00038 ;
00039 ;           ENDM
00040 ;
00041 ;
00042 ;           Test If A Device of SlaveAddr Is Present on Bus
00043 ;
00044 ;   The Slave Address Is put on the bus and if ACK it is present, if NACK not present
00045 ;   or maybe device is not responding. The presense can be checked constantly by a master
00046 ;   (for ex. the Operating System on an Access.Bus may constantly issue this command)
00047 ;
00048 ;   Assume the Slave Address (10 or 8 bit) is loaded in SlaveAddr
00049 ;   Set _10BitAddr bit in Control Reg to 1 if 10 bit Address slave else 0

```

```

00050 ;
00051 ; Returns 1 in _SlaveActive Bit if slave is responding else a 0
00052 ;
00053 ;
00054
0011 00055 IsSlaveActive
0011 1091 00056 bcf _Slave_RW ; set for write operation
0012 2057 00057 call TxmtStartBit ; send START bit
0013 206B 00058 call Txmt_Slave_Addr ; if successful, then _Txmt_Success bit is set
00059 ;
0014 1311 00060 bcf _SlaveActive
0015 1F90 00061 btfss _ACK_Error ; skip if NACK, device is not present or not responding
0016 1711 00062 bsf _SlaveActive ; ACK received, device present & listening
0017 205F 00063 call TxmtStopBit
0018 0008 00064 return
00065 ;
00066 ;*****
00067 ; I2C_WRITE
00068 ;
00069 ; A basic macro for writing a block of data to a slave
00070 ;
00071 ; Parameters :
00072 ; _BYTES_ #of bytes starting from RAM pointer _SourcePointer_
00073 ; _SourcePointer_ Data Start Buffer pointer in RAM (file Registers)
00074 ;
00075 ; Sequence :
00076 ; S-SlvAW-A-D[0]-A....A-D[N-1]-A-P
00077 ;
00078 ; If an error occurs then the routine simply returns and user should check for
00079 ; flags in Bus_Status Reg (for eg. _Txmt_Success flag)
00080 ;
00081 ; NOTE : The address of the slave must be loaded into SlaveAddress Registers, and 10 or 8 bit
00082 ; mode addressing must be set
00083 ;*****
00084
00085
00086 I2C_WR MACRO _BYTES_, _SourcePointer_
00087
00088 movlw _BYTES_
00089 movwf tempCount
00090 movlw _SourcePointer_
00091 movwf FSR
00092
00093 call _i2c_block_write
00094 call TxmtStopBit ; Issue a stop bit for slave to end transmission
00095
00096 ENDM

```



```

00097
0019      00098  _i2c_block_write:
0019 2057      00099          call    TxmtStartBit    ; send START bit
001A 1091      00100          bcf     _Slave_RW      ; set for write operation
001B 206B      00101          call    Txmt_Slave_Addr ; if successful, then _Txmt_Success bit is set
                                00102 ;
001C      00103  _block_wrl_loop:
001C 1E10      00104          btfss  _Txmt_Success
001D 0008      00105          return
001E 0800      00106          movf   INDF,W
001F 008E      00107          movwf  DataByte        ; start from the first byte starting at _DataPointer_
0020 0A84      00108          incf   FSR, F
0021 2095      00109          call  SendData        ; send next byte, bus is our's !
0022 0B96      00110          decfsz tempCount, F
0023 281C      00111          goto  _block_wrl_loop ; loop until desired bytes of data transmitted to slave
0024 0008      00112          return
                                00113 ;
                                00114 ;*****
                                00115
                                00116 ;*****
                                00117 ;                I2C_WRITE_SUB
                                00118 ;
00119 ; Writes a message just like I2C_WRITE, except that the data is preceeded by a sub-address
00120 ; to a slave device.
00121 ;           Eg. : A serial EEPROM would need an address of memory location for Random Writes
00122 ;
00123 ; Parameters :
00124 ;           _BYTES_           #of bytes starting from RAM pointer _SourcePointer_ (constant)
00125 ;           _SourcePointer_   Data Start Buffer pointer in RAM (file Registers)
00126 ;           _Sub_Address_     Sub-address of Slave (constant)
00127 ;
00128 ; Sequence :
00129 ;           S-SlvAW-A-SubA-A-D[0]-A....A-D[N-1]-A-P
00130 ;
00131 ; If an error occurs then the routine simply returns and user should check for
00132 ; flags in Bus_Status Reg (for eg. _Txmt_Success flag)
00133 ;
00134 ;           Returns : W register = 1 on success, else W register = 0
00135 ;
00136 ; NOTE : The address of the slave must be loaded into SlaveAddress Registers, and 10 or 8 bit
00137 ; mode addressing must be set
00138 ;
00139 ; COMMENTS :
00140 ;           I2C_WR may prove to be more efficient than this macro in most situations
00141 ;           Advantages will be found for Random Address Block Writes for Slaves with
00142 ;           Auto Increment Sub-Addresses (like Microchip's 24CXX series Serial EEPROMS)
00143 ;

```

```

00144 ;*****
00145
00146 I2C_WR_SUB      MACRO    _BYTES_, _SourcePointer_, _Sub_Address_
00147
00148             movlw    (_BYTES_ + 1)
00149             movwf   tempCount
00150
00151             movlw    (_SourcePointer_ - 1)
00152             movwf   FSR
00153
00154             movf    INDF,W
00155             movwf   StoreTemp_1      ; temporarily store contents of (_SourcePointer_ -1)
00156             movlw    _Sub_Address_
00157             movwf   INDF              ; store temporarily the sub-address at (_SourcePointer_ -1)
00158
00159             call    _i2c_block_write      ; write _BYTES_+1 block of data
00160
00161             movf    StoreTemp_1,W
00162             movwf   (_SourcePointer_ - 1) ; restore contents of (_SourcePointer_ - 1)
00163
00164             call    TxmtStopBit          ; Issue a stop bit for slave to end transmission
00165
00166             ENDM
00167
00168 ;*****
00169 ;                               I2C_WR_SUB_SWINC
00170 ;
00171 ; Parameters :
00172 ;           _BYTES_           #of bytes starting from RAM pointer _SourcePointer_ (constant)
00173 ;           _SourcePointer_   Data Start Buffer pointer in RAM (file Registers)
00174 ;           _Sub_Address_     Sub-address of Slave (constant)
00175 ;
00176 ; Sequence :
00177 ;           S-SlvAW-A-(SubA+0)-A-D[0]-A-P
00178 ;           S-SlvAW-A-(SubA+1)-A-D[1]-A-P
00179 ;           and so on until #of Bytes
00180 ;
00181 ; If an error occurs then the routine simply returns and user should check for
00182 ; flags in Bus_Status Reg (for eg. _Txmt_Success flag)
00183 ;
00184 ; Returns :           W register = 1 on success, else W register = 0
00185 ;
00186 ; COMMENTS : Very In-efficient, Bus is given up after every Byte Write
00187 ;
00188 ;           Some I2C devices addressed with a sub-address do not increment automatically
00189 ; after an access of each byte. Thus a block of data sent must have a sub-address
00190 ; followed by a data byte.

```

```

00191 ;
00192 ;*****
00193
00194 I2C_WR_SUB_SWINC      MACRO   _BYTES_, _SourcePointer_, _Sub_Address_
00195
00196         variable i           ; TEMP ????: Assembler Does Not Support This
00197
00198         i = 0
00199
00200         while (i < _BYTES_)
00201             movf    (_SourcePointer_ + i),W
00202             movwf   SrcPtr
00203             movf    (_Sub_Address_ + i),W
00204             movwf   SubAddr
00205             call    _i2c_byte_wr_sub      ; write a byte of data at sub address
00206
00207             i++
00208         endwhile
00209
00210         ENDM
00211
00212 ;
00213 ;
00214 ; Write 1 Byte Of Data (in SrcPtr) to slave at sub-address (SubAddr)
00215 ;
00216
0025      00217 _i2c_byte_wr_sub:
0025 2057      00218         call    TxmtStartBit    ; send START bit
0026 1091      00219         bcf     _Slave_RW      ; set for write operation
0027 206B      00220         call    Txmt_Slave_Addr ; if successful, then _Txmt_Success bit is set
0028 1E10      00221         btfss   _Txmt_Success
0029 2835      00222         goto    _block_wrl_fail ; end
002A 0814      00223         movf    SubAddr,W
002B 008E      00224         movwf   DataByte      ; start from the first byte starting at _DataPointer_
002C 2095      00225         call    SendData      ; send next byte
002D 1E10      00226         btfss   _Txmt_Success
002E 2835      00227         goto    _block_wrl_fail ; end
002F 0815      00228         movf    SrcPtr,W
0030 008E      00229         movwf   DataByte      ; start from the first byte starting at _DataPointer_
0031 2095      00230         call    SendData      ; send next byte
0032 1E10      00231         btfss   _Txmt_Success
0033 2835      00232         goto    _block_wrl_fail ; failed, return 0 in W register
0034 2837      00233         goto    _block_wrl_pass ; successful, return 1 in W register
00234 ;
00235 ; return back to called routine from either _block_wrl_pass or _block_wrl_fail
00236 ;
0035      00237 _block_wrl_fail:

```

```

0035 205F      00238          call    TxmtStopBit    ; Issue a stop bit for slave to end transmission
0036 3400      00239          retlw   FALSE
0037          00240  _block_wrl_pass:
0037 205F      00241          call    TxmtStopBit    ; Issue a stop bit for slave to end transmission
0038 3401      00242          retlw   TRUE
00243 ;
00244 ;
00245 ;*****
00246 ;
00247 ;                I2C_WR_MEM_BYTE
00248 ;
00249 ; Some I2C devices like a EEPROM need to wait fo some time after every byte write
00250 ; (when entered into internal programming mode). This MACRO is same as I2C_WR_SUB_SWINC,
00251 ; but in addition adds a delay after each byte.
00252 ;         Some EEPROM memories (like Microchip's 24Cxx Series have on-chip data buffer), and hence
00253 ;         this routine is not efficient in these cases. In such cases use I2C_WR or I2C_WR_SUB
00254 ;         for a block of data and then insert a delay until the whole buffer is written.
00255 ;
00256 ; Parameters :
00257 ;         _BYTES_                #of bytes starting from RAM pointer _SourcePointer_ (constant)
00258 ;         _SourcePointer_        Data Start Buffer pointer in RAM (file Registers)
00259 ;         _Sub_Address_         Sub-address of Slave (constant)
00260 ;
00261 ; Sequence :
00262 ;         S-SlvAW-A-(SubA+0)-A-D[0]-A-P
00263 ;         Delay 1 mSec          ; The user can chngae this value to desired delay
00264 ;         S-SlvAW-A-(SubA+1)-A-D[1]-A-P
00265 ;         Delay 1 mSec
00266 ;         and so on until #of Bytes
00267 ;
00268 ;*****
00269 ;
00270 I2C_WR_BYTE_MEM      MACRO    _BYTES_, _SourcePointer_, _Sub_Address_
00271 ;
00272 ;         variable i                ; TEMP ???? : Assembler Does Not Support This
00273 ;
00274 ;         i = 0
00275 ;
00276 ;         while (i < _BYTES_)
00277 ;             movf    (_SourcePointer_ + i),W
00278 ;             movwf   SrcPtr
00279 ;             movf    (_Sub_Address_ + i),W
00280 ;             movwf   SubAddr
00281 ;             call    _i2c_byte_wr_sub    ; write a byte of data at sub address
00282 ;             call    Delay50uSec
00283 ;
00284 ;             i++

```

```

00285             endw
00286
00287
00288             ENDM
00289
00290 ;*****
00291 ;             I2C_WR_MEM_BUF
00292 ;
00293 ;   This Macro/Function writes #of _BYTES_ to an I2C memory device. However
00294 ;   some devices, esp. EEPROMs must wait while the device enters into programming
00295 ;   mode. But some devices have an onchip temp data hold buffer and is used to
00296 ;   store data before the device actually enters into programming mode.
00297 ;   For example, the 24C04 series of Serial EEPROMs from Microchip
00298 ;   have an 8 byte data buffer. So one can send 8 bytes of data at a time
00299 ;   and then the device enters programming mode. The master can either wait
00300 ;   until a fixed time and then retry to program or can continuously poll
00301 ;   for ACK bit and then transmit the next Block of data for programming
00302 ;
00303 ; Parameters :
00304 ;   _BYTES_             # of bytes to write to memory
00305 ;   _SourcePointer_    Pointer to the block of data
00306 ;   _SubAddress_       Sub-address of the slave
00307 ;   _Device_BUF_SIZE_  The on chip buffer size of the i2c slave
00308 ;
00309 ; Sequence of operations
00310 ;   I2C_SUB_WR operations are performed in loop and each time
00311 ;   data buffer of BUF_SIZE is output to the device. Then
00312 ;   the device is checked for busy and when not busy another
00313 ;   block of data is written
00314 ;
00315 ;
00316 ;*****
00317
00318 I2C_WR_BUF_MEM MACRO  _BYTES_, _SourcePointer_, _SubAddress_, _Device_BUF_SIZE_
00319
00320
00321             variable i, j
00322
00323
00324             if ( !_BYTES_ )
00325                 exitm
00326
00327             elif ( _BYTES_ <= _Device_BUF_SIZE_ )
00328
00329                 I2C_WR_SUB      _BYTES_, _SourcePointer_, _SubAddress_
00330
00331                 exitm

```

```

00332
00333         else
00334
00335             i = 0
00336             j = (_BYTES_ / _Device_BUF_SIZE_)
00337             while (i < j)
00338
00339 I2C_WR_SUB  _Device_BUF_SIZE_, (_SourcePointer_ + i*_Device_BUF_SIZE_),(_SubAddress_ + i*_Device_BUF_SIZE_)
00340
00341             call    IsSlaveActive
00342             btffs  _SlaveActive
00343             goto   $-2
00344
00345             i++
00346             endw
00347
00348             j = (_BYTES_ - i*_Device_BUF_SIZE_)
00349
00350             if (j)
00351 I2C_WR_SUB j, (_SourcePointer_ + i*_Device_BUF_SIZE_), (_SubAddress_ + i*_Device_BUF_SIZE_)
00352             endif
00353
00354         endif
00355
00356     ENDM
00357
00358
00359 ;*****
00360 ;
00361 ;             I2C_READ
00362 ;
00363 ; The basic MACRO/procedure to read a block message from a slave device
00364 ;
00365 ; Parameters :
00366 ;     _BYTES_           : constant : #of bytes to receive
00367 ;     _DestPointer_    : destination pointer of RAM (File Registers)
00368 ;
00369 ; Sequence :
00370 ;     S-SlvAR-A-D[0]-A-....-A-D[N-1]-N-P
00371 ;
00372 ; If last byte, then Master will NOT Acknowledge (send NACK)
00373 ;
00374 ; NOTE : The address of the slave must be loaded into SlaveAddress Registers, and 10 or 8 bit
00375 ; mode addressing must be set
00376 ;
00377 ;*****
00378

```

```

00379 I2C_READ      MACRO   _BYTES_, _DestPointer_
00380
00381
00382              movlw   (_BYTES_ -1)
00383              movwf   tempCount           ; -1 because, the last byte is used out of loop
00384              movlw   _DestPointer_
00385              movwf   FSR                 ; FIFO destination address pointer
00386
00387              call    _i2c_block_read
00388
00389              ENDM
00390
0039 00391 _i2c_block_read:
0039 2057 00392      call    TxmtStartBit   ; send START bit
003A 1491 00393      bsf     _Slave_RW       ; set for read operation
003B 1111 00394      bcf     _Last_Byte_Rcv  ; not a last byte to rcv
003C 206B 00395      call    Txmt_Slave_Addr ; if successful, then Txmt_Success bit is set
003D 1A10 00396      btfsc   _Txmt_Success
003E 2841 00397      goto    _block_rdl_loop ; end
003F 205F 00398      call    TxmtStopBit    ; Issue a stop bit for slave to end transmission
0040 3400 00399      retlw   FALSE         ; Error : may be device not responding
00400 ;
0041 00401 _block_rdl_loop:
0041 20CC 00402      call    GetData
0042 080E 00403      movf    DataByte,W
0043 0080 00404      movwf   INDF           ; start receiving data, starting at Destination Pointer
0044 0A84 00405      incf   FSR, F
0045 0B96 00406      decfsz tempCount, F
0046 2841 00407      goto    _block_rdl_loop ; loop until desired bytes of data transmitted to slave
0047 1511 00408      bsf     _Last_Byte_Rcv  ; last byte to rcv, so send NACK
0048 20CC 00409      call    GetData
0049 080E 00410      movf    DataByte,W
004A 0080 00411      movwf   INDF
004B 205F 00412      call    TxmtStopBit    ; Issue a stop bit for slave to end transmission
004C 3401 00413      retlw   TRUE
00414
00415
00416 ;*****
00417 ;
00418 ;
00419 ; I2C_READ_SUB
00419 ; This MACRO/Subroutine reads a message from a slave device preceeded by a write of the sub-address
00420 ; Between the sub-address write & the following reads, a STOP condition is not issued and
00421 ; a "REPEATED START" condition is used so that an other master will not take over the bus,
00422 ; and also that no other master will overwrite the sub-address of the same slave.
00423 ;
00424 ; This function is very commonly used in accessing Random/Sequential reads from a
00425 ; memory device (e.g : 24Cxx serial of Serial EEPROMs from Microchip).

```

```

00426 ;
00427 ; Parameters :
00428 ;     _BYTES_      # of bytes to read
00429 ;     _DestPointer_ The destination pointer of data to be received.
00430 ;     _SubAddress_  The sub-address of the slave
00431 ;
00432 ; Sequence :
00433 ;     S-SlvAW-A-SubAddr-A-S-SlvAR-A-D[0]-A-....-A-D[N-1]-N-P
00434 ;
00435 ;
00436 ;*****
00437
00438 I2C_READ_SUB    MACRO    _BYTES_, _DestPointer_, _SubAddress_
00439
00440             bcf     _Slave_RW      ; set for write operation
00441             call   TxmtStartBit    ; send START bit
00442             call   Txmt_Slave_Addr ; if successful, then _Txmt_Success bit is set
00443
00444             movlw  _SubAddress_
00445             movwf  DataByte        ; START address of EEPROM(slave 1)
00446             call   SendData        ; write sub address
00447 ;
00448 ; do not send STOP after this, use REPEATED START condition
00449 ;
00450
00451             I2C_READ _BYTES_, _DestPointer_
00452
00453
00454             ENDM
00455
00456
00457
00458 ;*****
00459 ;
00460 ;             I2C_READ_STATUS
00461 ;
00462 ; This Macro/Function reads a status word (1 byte) from slave. Several I2C devices can
00463 ; send a status byte upon reception of a control byte
00464 ; This is basically same as I2C_READ MACRO for reading a single byte
00465 ;
00466 ; For example, in a Serial EEPROM (Microchip's 24Cxx serial EEPROMs) will send the memory
00467 ; data at the current address location
00468 ;
00469 ; On success W register = 1 else = 0
00470 ;
00471 ;*****
00472

```



```

00473 I2C_READ_STATUS MACRO   _DestPointer_
00474
00475
00476         call    TxmtStartBit    ; send START bit
00477         bsf     _Slave_RW       ; set for read operation
00478         call    Txmt_Slave_Addr ; if successful, then _Txmt_Success bit is set
00479         btfsc   _Txmt_Success
00480         goto    _byte_rdl_loop   ; read a byte
00481         call    TxmtStopBit     ; Issue a stop bit for slave to end transmission
00482         retlw   FALSE           ; Error : may be device not responding
00483 _byte_rdl_loop:
00484         bsf     _Last_Byte_Rcv   ; last byte to rcv, so send NACK
00485         call    GetData
00486         movf    DataByte,W
00487         movwf   _DestPointer_
00488         call    TxmtStopBit     ; Issue a stop bit for slave to end transmission
00489         btfss   _Rcv_Success
00490         retlw   FALSE
00491         retlw   TRUE
00492
00493         ENDM
00494
00495 ;*****
00496
00497 I2C_READ_BYTE   MACRO   _DestPointer_
00498
00499         I2C_READ_STATUS MACRO   _DestPointer_
00500
00501         ENDM
00502
00503
00504 ;*****
00505 ;
00506 ;
00507 ;
00508 ; This Macro writes 2 Blocks of Data (variable length) to a slave at a sub-address. This
00509 ; may be useful for devices which need 2 blocks of data in which the first block may be an
00510 ; extended address of a slave device. For example, a large I2C memory device, or a teletext
00511 ; device with an extended addressing scheme, may need multiple bytes of data in the 1st block
00512 ; that represents the actual physical address and is followed by a 2nd block that actually
00513 ; represents the data.
00514 ;
00515 ; Parameters :
00516 ;
00517 ;         _BYTES1_           1st block #of bytes
00518 ;         _SourcePointer1_  Start Pointer of the 1st block
00519 ;         _SubAddress_      Sub-Address of slave

```

```

00520 ;           _BYTES2_           2st block #of bytes
00521 ;           _SourcePointer2_   Start Pointer of the 2nd block
00522 ;
00523 ; Sequence :
00524 ;           S-SlvW-A-SubA-A-D1[0]-A-....-D1[N-1]-A-D2[0]-A-....A-D2[M-1]-A-P
00525 ;
00526 ; Note : This MACRO is basically same as calling I2C_WR_SUB twice, but
00527 ;           a STOP bit is not sent (bus is not given up) in between
00528 ;           the two I2C_WR_SUB
00529 ;
00530 ; Check Txmt_Success flag for any transmission errors
00531 ;
00532 ;*****
00533
00534 I2C_WR_SUB_WR  MACRO  _COUNT1_, _SourcePointer1_, _Sub_Address_, _COUNT2_, _SourcePointer2_
00535
00536             movlw  (_COUNT1_ + 1)
00537             movwf  tempCount
00538             movlw  (_SourcePointer1_ - 1)
00539             movwf  FSR
00540
00541             movf   INDF,W
00542             movwf  StoreTemp_1      ; temporarily store contents of (_SourcePointer_ -1)
00543             movlw  _Sub_Address_
00544             movwf  INDF             ; store temporarily the sub-address at (_SourcePointer_ -1)
00545             call  _i2c_block_write   ; write _BYTES_+1 block of data
00546 ;
00547             movf   StoreTemp_1,W
00548             movwf  (_SourcePointer1_ - 1)  ; restore contents of (_SourcePointer_ - 1)
00549 ; Block 1 write over
00550 ; Send Block 2
00551             movlw  _COUNT2_
00552             movwf  tempCount
00553             movlw  _SourcePointer2_
00554             movwf  FSR
00555             call  _block_wr1_loop
00556 ;
00557             call  TxmtStopBit      ; Issue a stop bit for slave to end transmission
00558
00559             ENDM
00560
00561
00562 ;*****
00563 ;
00564 ;           I2C_WR_SUB_RD
00565 ;
00566 ; This macro writes a block of data from SourcePointer of length _COUNT1_ to a slave

```

```

00567 ;         at sub-address and then Reads a block of Data of length _COUNT2_ to destination
00568 ;         address pointer
00569 ;
00570 ;
00571 ; Message Structure :
00572 ;         S-SlvW-A-SubA-A-D1[0]-A-.....-A-D1[N-1]-A-S-SlvR-A-D2[0]-A-.....-A-D2[M-1]-N-P
00573 ;
00574 ; Parameters :
00575 ;         _COUNT1_           Length Of Source Buffer
00576 ;         _SourcePointer_     Source Pointer Address
00577 ;         _Sub_Address_       The Sub Address Of the slave
00578 ;         _COUNT2_          The length of Destination Buffer
00579 ;         _DestPointer_       The start address of Destination Pointer
00580 ;
00581 ;*****
00582
00583 I2C_WR_SUB_RD  MACRO  _COUNT1_, _SourcePointer_, _Sub_Address_, _COUNT2_, _DestPointer_
00584
00585             movlw  (_COUNT1_ + 1)
00586             movwf  tempCount
00587             movlw  (_SourcePointer_ - 1)
00588             movwf  FSR
00589
00590             movf   INDF,W
00591             movwf  StoreTemp_1      ; temporarily store contents of (_SourcePointer_ -1)
00592             movlw  _Sub_Address_
00593             movwf  INDF              ; store temporarily the sub-address at (_SourcePointer_ -1)
00594             call   _i2c_block_write      ; write _BYTES_+1 block of data
00595 ;
00596             movf   StoreTemp_1,W
00597             movwf  (_SourcePointer_1_ - 1)  ; restore contents of (_SourcePointer_ - 1)
00598 ;
00599 ; Without sending a STOP bit, read a block of data by using a REPEATED
00600 ; Start Condition
00601 ;
00602             I2C_READ      _COUNT2_, _DestPointer_
00603
00604             ENDM
00605
00606
00607 ;*****
00608 ;
00609             I2C_WR_COM_WR
00610 ;
00611 ; This Macro write 2 blocks of data buffers to a slave in one message. This way no need to give up
00612 ; the bus after sending the first block.
00613 ; For example, this kind of transaction is used in an LCD driver where a

```

```

00614 ;      block of control & addresss info is needed and then
00615 ;      another block of actual data to be displayed is needed.
00616 ;
00617 ;
00618 ; Message Structure :
00619 ;      S-SlvW-A-D1[0]-A-....A-D1[N-1]-A-D2[0]-A-.....-A-D2[M-1]-A-P
00620 ; NOTE : This message is same as calling two I2C_WR Macros, except that
00621 ;      the bus is not given up between the sending of 2 blocks (this is
00622 ;      done by not sending a STOP bit inbetween)
00623 ;
00624 ; Parameters :
00625 ;      _COUNT1_          Length Of Source Buffer #1
00626 ;      _SourcePointer1_  Source Pointer Address of 1st buffer
00627 ;      _COUNT2_          The length of Destination Buffer
00628 ;      _SourcePointer2_  Source Pointer Address of 2nd Buffer
00629 ;
00630 ;*****
00631
00632 I2C_WR_COM_WR  MACRO  _COUNT1_, _SourcePointer1_, _COUNT2_, _SourcePointer2_
00633
00634             movlw  _COUNT1_
00635             movwf  tempCount
00636             movlw  _SourcePointer1_
00637             movwf  FSR
00638             call   _i2c_block_write
00639 ;
00640 ; First block sent, now send 2nd block of data
00641 ;
00642             movlw  _COUNT2_
00643             movwf  tempCount
00644             movlw  _SourcePointer2__
00645             movwf  FSR
00646             call   _block_wrl_loop
00647 ;
00648             call   TxmtStopBit      ; End of Double buffer txmt
00649
00650             ENDM
00651
00652
00653 ;*****
00654 ;      INCLUDE I2C Low Level Routines Here
00655 ;*****
00656
00657             include "i2c_low.inc"
00001 ;*****
00002 ;
00003 ;      Low Level I2C Routines

```

```

00004 ;
00005 ;     Single Master Transmitter & Single Master Receiver Routines
00006 ;     These routines can very easily be converted to Multi-Master System
00007 ;     when PIC16C6X with on chip I2C Slave Hardware, Start & Stop Bit
00008 ;     detection is available.
00009 ;
00010 ;     The generic high level routines are given in I2C_HIGH.ASM
00011 ;
00012 ;
00013 ;     Program:           I2C_LOW.ASM
00014 ;     Revision Date:
00015 ;                   1-16-97     Compatibility with MPASMWIN 1.40
00016 ;
00017 ;*****
00018
00019
00020
00021
00022
00023 ;*****
00024 ;                   I2C Bus Initialization
00025 ;
00026 ;*****
004D 00027 InitI2CBus_Master:
00028
004D 1283 00029         bcf     STATUS,RP0
004E 0806 00030         movf    PORTB,W
004F 39FC 00031         andlw   0xFC           ; do not use BSF & BCF on Port Pins
0050 0086 00032         movwf   PORTB         ; set SDA & SCL to zero. From Now on, simply play with tris
00033         RELEASE_BUS
0051 1683         M       bsf     STATUS,RP0     ; select Bank1
0052 1486         M       bsf     _SDA           ; tristate SDA
0053 1406         M       bsf     _SCL           ; tristate SCL
           M ;       bcf     _Bus_Busy     ; Bus Not Busy, TEMP ????, set/clear on Start & Stop
0054 0190 00034         clrf    Bus_Status     ; reset status reg
0055 0191 00035         clrf    Bus_Control   ; clear the Bus_Control Reg, reset to 8 bit addressing
0056 0008 00036         return
00037 ;
00038 ;*****
00039 ;                   Send Start Bit
00040 ;
00041 ;*****
00042
0057 00043 TxmtStartBit:
0057 1683 00044         bsf     STATUS,RP0     ; select Bank1
0058 1486 00045         bsf     _SDA           ; set SDA high
0059 1406 00046         bsf     _SCL           ; clock is high

```

```

00047 ;
00048 ; Setup time for a REPEATED START condition (4.7 uS)
00049 ;
005A 210D      00050      call    Delay40uSec    ; only necessary for setup time
00051 ;
005B 1086      00052      bcf     _SDA           ; give a falling edge on SDA while clock is high
00053 ;
005C 210B      00054      call    Delay47uSec    ; only necessary for START HOLD time
00055 ;
005D 1410      00056      bsf     _Bus_Busy      ; on a start condition bus is busy
00057 ;
005E 0008      00058      return
00059
00060
00061 ;*****
00062 ;                               Send Stop Bit
00063 ;
00064 ;*****
00065
005F           00066 TxmtStopBit:
005F 1683      00067      bsf     STATUS,RP0    ; select Bank1
0060 1006      00068      bcf     _SCL
0061 1086      00069      bcf     _SDA           ; set SDA low
0062 1406      00070      bsf     _SCL           ; Clock is pulled up
0063 210D      00071      call    Delay40uSec    ; Setup Time For STOP Condition
0064 1486      00072      bsf     _SDA           ; give a rising edge on SDA while CLOCK is high
00073 ;
00074      if _ENABLE_BUS_FREE_TIME
00075 ; delay to make sure a START bit is not sent immediately after a STOP, ensure BUS Free Time tBUF
00076 ;
0065 210B      00077      call    Delay47uSec
00078      endif
00079 ;
0066 1010      00080      bcf     _Bus_Busy      ; on a stop condition bus is considered Free
00081 ;
0067 0008      00082      return
00083
00084
00085 ;*****
00086 ;                               Abort Transmission
00087 ;
00088 ;   Send STOP Bit & set Abort Flag
00089 ;*****
00090
0068           00091 AbortTransmission:
00092
0068 205F      00093      call    TxmtStopBit

```

```

0069 1490      00094          bsf      _Abort
006A 0008      00095          return
00096
00097 ;*****
00098 ;                      Transmit Address (1st Byte)& Put in Read/Write Operation
00099 ;
00100 ; Transmits Slave Addr On the 1st byte and set LSB to R/W operation
00101 ; Slave Address must be loaded into SlaveAddr reg
00102 ; The R/W operation must be set in Bus_Status Reg (bit _SLAVE_RW): 0 for Write & 1 for Read
00103 ;
00104 ; On Success, return TRUE in W register, else FALSE in W register
00105 ;
00106 ; If desired, the failure may tested by the bits in Bus Status Reg
00107 ;
00108 ;*****
00109
006B          00110 Txmt_Slave_Addr:
006B 1390      00111          bcf      _ACK_Error          ; reset Acknowledge error bit
006C 1C11      00112          btfss   _10BitAddr
006D 2886      00113          goto    SevenBitAddr
00114 ;
006E 1C91      00115          btfss   _Slave_RW
006F 287D      00116          goto    TenBitAddrWR          ; For 10 Bit WR simply send 10 bit addr
00117 ;
00118 ; Required to READ a 10 bit slave, so first send 10 Bit for WR & Then Repeated Start
00119 ; and then Hi Byte Only for read operation
00120 ;
0070          00121 TenBitAddrRd:
00122
0070 1091      00123          bcf      _Slave_RW          ; temporarily set for WR operation
0071 207D      00124          call    TenBitAddrWR
0072 1E10      00125          btfss   _Txmt_Success          ; skip if successful
0073 3400      00126          retlw   FALSE
00127
0074 2057      00128          call    TxmtStartBit          ; send A REPEATED START condition
0075 1491      00129          bsf      _Slave_RW          ; For 10 bit slave Read
00130
0076 080D      00131          movf    SlaveAddr+1,W
0077 008E      00132          movwf   DataByte
0078 140E      00133          bsf      DataByte,LSB          ; Read Operation
0079 2095      00134          call    SendData          ; send ONLY high byte of 10 bit addr slave
007A 288C      00135          goto    _AddrSendTest          ; 10 Bit Addr Send For Slave Read Over
00136 ;
00137 ; if successfully transmitted, expect an ACK bit
00138 ;
007B 1E10      00139          btfss   _Txmt_Success          ; if not successful, generate STOP & abort transfer
007C 2890      00140          goto    _AddrSendFail

```

```

00141 ;
00142
007D 007D 008D 00143 TenBitAddrWR:
00144
007D 080D 00145      movf   SlaveAddr+1,W
007E 008E 00146      movwf  DataByte
007F 100E 00147      bcf    DataByte,LSB      ; WR Operation
00148 ;
00149 ; Ready to transmit data : If Interrupt Driven (i.e if Clock Stretched LOW Enabled)
00150 ; then save RETURN Address Pointer
00151 ;
0080 2095 00152      call   SendData      ; send high byte of 10 bit addr slave
00153 ;
00154 ; if successfully transmitted, expect an ACK bit
00155 ;
0081 1E10 00156      btfss  _Txmt_Success      ; if not successful, generate STOP & abort transfer
0082 2890 00157      goto   _AddrSendFail
00158 ;
0083 080C 00159      movf   SlaveAddr,W
0084 008E 00160      movwf  DataByte      ; load addr to DatByte for transmission
0085 288B 00161      goto   EndTxmtAddr
00162
0086      00163 SevenBitAddr:
0086 080C 00164      movf   SlaveAddr,W
0087 008E 00165      movwf  DataByte      ; load addr to DatByte for transmission
0088 100E 00166      bcf    DataByte,LSB
0089 1891 00167      btfs   _Slave_RW      ; if skip then write operation
008A 140E 00168      bsf    DataByte,LSB      ; Read Operation
00169
008B      00170 EndTxmtAddr:
008B 2095 00171      call   SendData      ; send 8 bits of address, bus is our's
00172 ;
00173 ; if successfully transmitted, expect an ACK bit
00174 ;
008C      00175 _AddrSendTest:
008C 1E10 00176      btfss  _Txmt_Success      ; skip if successful
008D 2890 00177      goto   _AddrSendFail
008E 0064 00178      clrwdt
008F 3401 00179      retlw  TRUE
00180 ;
0090      00181 _AddrSendFail:
0090 0064 00182      clrwdt
0091 1F90 00183      btfss  _ACK_Error
0092 3400 00184      retlw  FALSE      ; Addr Txmt Unsuccessful, so return 0
00185 ;
00186 ; Address Not Acknowledged, so send STOP bit
00187 ;

```



```

0093 205F      00188      call    TxmtStopBit
0094 3400      00189      retlw   FALSE                ; Addr Txmt Unsuccessful, so return 0
                                00190      ;
                                00191      ;*****
                                00192      ;           Transmit A Byte Of Data
                                00193      ;
                                00194      ; The data to be transmitted must be loaded into DataByte Reg
                                00195      ; Clock stretching is allowed by slave. If the slave pulls the clock low, then, the stretch is detected
                                00196      ; and INT Interrupt on Rising edge is enabled and also TMR0 timeout interrupt is enabled
                                00197      ;           The clock stretching slows down the transmit rate because all checking is done in
                                00198      ;           software. However, if the system has fast slaves and needs no clock stretching, then
                                00199      ;           this feature can be disabled during Assembly time by setting
                                00200      ;           _CLOCK_STRETCH_ENABLED must be set to FALSE.
                                00201      ;
                                00202      ;*****
0095          00203 SendData:
                                00204
                                00205      ;
                                00206      ; TXmtByte & Send Data are same, Can check errors here before calling TxmtByte
                                00207      ; For future compatibility, the user MUST call SendData & NOT TxmtByte
                                00208      ;
0095 2896      00209      goto    TxmtByte
                                00210
                                00211      ;
0096          00212 TxmtByte:
0096 080E      00213          movf   DataByte,W
0097 0093      00214          movwf  DataByteCopy    ; make copy of DataByte
0098 1510      00215          bsf   _Txmt_Progress  ; set Bus status for txmt progress
0099 1210      00216          bcf   _Txmt_Success   ; reset status bit
009A 3008      00217          movlw  0x08
009B 008F      00218          movwf  BitCount
009C 1683      00219          bsf   STATUS,RP0
                                00220          if _CLOCK_STRETCH_CHECK
                                00221      ;           set TMR0 to INT CLK timeout for 1 mSec
                                00222      ;           do not disturb user's selection of RPUB in OPTION Register
                                00223      ;
                                00224          movf   OPTION_REG,W
009E 39C3      00225          andlw  _OPTION_INIT    ; defined in I2C.H header file
009F 0081      00226          movwf  OPTION_REG
                                00227          endif
                                00228
009D 0801      00229 TxmtNextBit:
00A0 0064      00230          clrwdt                ; clear WDT, set for 18 mSec
00A1 1006      00231          bcf   _SCL
00A2 0D93      00232          rlf   DataByteCopy, F ; MSB first, Note DataByte Is Lost
00A3 1086      00233          bcf   _SDA
00A4 1803      00234          btfsc STATUS,C

```

```

00A5 1486      00235          bsf      _SDA
00A6 210B      00236          call     Delay47uSec      ; guarantee min LOW TIME tLOW & Setup time
00A7 1406      00237          bsf      _SCL             ; set clock high, check if clock is high, else clock being stretched
00A8 210D      00238          call     Delay40uSec     ; guarantee min HIGH TIME tHIGH
00239          if _CLOCK_STRETCH_CHECK
00A9 1283      00240          bcf      STATUS,RP0
00AA 0181      00241          clrfs   TMR0             ; clear TMR0
00AB 110B      00242          bcf      INTCON,T0IF     ; clear any pending flags
00AC 168B      00243          bsf      INTCON,T0IE     ; enable TMR0 Interrupt
00AD 1391      00244          bcf      _TIME_OUT_     ; reset timeout error flag
00AE          00245 Check_SCL_1:
00AE 1B91      00246          btfs    _TIME_OUT_     ; if TMR0 timeout or Error then Abort & return
00AF 28FC      00247          goto    Bus_Fatal_Error ; Possible FATAL Error on Bus
00B0 1283      00248          bcf      STATUS,RP0
00B1 1C06      00249          btfs    _SCL             ; if clock not being stretched, it must be high
00B2 28AE      00250          goto    Check_SCL_1     ; loop until SCL high or TMR0 timeout interrupt
00B3 128B      00251          bcf      INTCON,T0IE     ; Clock good, disable TMR0 interrupts
00B4 1683      00252          bsf      STATUS,RP0
00253          endif
00B5 0B8F      00254          decfsz  BitCount, F
00B6 28A0      00255          goto    TxmtNextBit
00256          ;
00257          ; Check For Acknowledge
00258          ;
00B7 1006      00259          bcf      _SCL             ; reset clock
00B8 1486      00260          bsf      _SDA             ; Release SDA line for Slave to pull down
00B9 210B      00261          call     Delay47uSec     ; guarantee min LOW TIME tLOW & Setup time
00BA 1406      00262          bsf      _SCL             ; clock for slave to ACK
00BB 210D      00263          call     Delay40uSec     ; guarantee min HIGH TIME tHIGH
00BC 1283      00264          bcf      STATUS,RP0     ; select Bank0 to test PortB pin SDA
00BD 1886      00265          btfs    _SDA             ; SDA should be pulled low by slave if OK
00BE 28C5      00266          goto    _TxmtErrorAck
00267          ;
00BF 1683      00268          bsf      STATUS,RP0
00C0 1006      00269          bcf      _SCL             ; reset clock
00270          ;
00C1 1110      00271          bcf      _Txmt_Progress  ; reset TXMT bit in Bus Status
00C2 1610      00272          bsf      _Txmt_Success   ; transmission successful
00C3 1390      00273          bcf      _ACK_Error      ; ACK OK
00C4 0008      00274          return
00C5          00275 _TxmtErrorAck:
00276          RELEASE_BUS
00C5 1683      M          bsf      STATUS,RP0     ; select Bank1
00C6 1486      M          bsf      _SDA             ; tristate SDA
00C7 1406      M          bsf      _SCL             ; tristate SCL
00C8          M          bcf      _Bus_Busy       ; Bus Not Busy, TEMP ???? , set/clear on Start & Stop
00C8 1110      00277          bcf      _Txmt_Progress  ; reset TXMT bit in Bus Status

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```

00C9 1210      00278          bcf      _Txmt_Success  ; transmission NOT successful
00CA 1790      00279          bsf      _ACK_Error    ; No ACK From Slave
00CB 0008      00280          return
00281 ;
00282 ;*****
00283 ;
00284 ;          Receive  A Byte Of Data From Slave
00285 ;
00286 ;  assume address is already sent
00287 ;  if last byte to be received, do not acknowledge slave (last byte is tested from
00288 ;  _Last_Byte_Rcv bit of control reg)
00289 ;  Data Received on successful reception is in DataReg register
00290 ;
00291 ;
00292 ;*****
00293 ;
00294
00CC          00295 GetData:
00CC 28CD      00296          goto     RcvByte
00297 ;
00CD          00298 RcvByte:
00299
00CD 1590      00300          bsf      _Rcv_Progress ; set Bus status for txmt progress
00CE 1290      00301          bcf      _Rcv_Success  ; reset status bit
00302
00CF 3008      00303          movlw   0x08
00D0 008F      00304          movwf   BitCount
00305          if _CLOCK_STRETCH_CHECK
00D1 1683      00306          bsf      STATUS,RP0
00307 ;          set TMR0 to INT CLK timeout for 1 mSec
00308 ;          do not disturb user's selection of RPBUS in OPTION Register
00309 ;
00D2 0801      00310          movf    OPTION_REG,W
00D3 39C3      00311          andlw  _OPTION_INIT    ; defined in I2C.H header file
00D4 0081      00312          movwf  OPTION_REG
00313          endif
00314
00D5          00315 RcvNextBit:
00D5 0064      00316          clrwdt          ; clear WDT, set for 18 mSec
00D6 1683      00317          bsf      STATUS,RP0 ; Bank1 for TRIS manipulation
00D7 1006      00318          bcf      _SCL
00D8 1486      00319          bsf      _SDA          ; can be removed from loop
00D9 210B      00320          call   Delay47uSec    ; guarantee min LOW TIME tLOW & Setup time
00DA 1406      00321          bsf      _SCL          ; clock high, data sent by slave
00DB 210D      00322          call   Delay40uSec    ; guarantee min HIGH TIME tHIGH
00323          if _CLOCK_STRETCH_CHECK
00DC 1283      00324          bcf      STATUS,RP0

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```

00DD 0181      00325          clrfs   TMR0          ; clear TMR0
00DE 110B      00326          bcf     INTCON,T0IF  ; clear any pending flags
00DF 168B      00327          bsf     INTCON,T0IE  ; enable TMR0 Interrupt
00E0 1391      00328          bcf     _TIME_OUT_  ; reset timeout error flag
00E1           00329 Check_SCL_2:
00E1 1B91      00330          btfsc   _TIME_OUT_  ; if TMR0 timeout or Error then Abort & return
00E2 28FC      00331          goto    Bus_Fatal_Error ; Possible FATAL Error on Bus
00E3 1283      00332          bcf     STATUS,RP0
00E4 1C06      00333          btfss   _SCL        ; if clock not being stretched, it must be high
00E5 28E1      00334          goto    Check_SCL_2 ; loop until SCL high or TMR0 timeout interrupt
00E6 128B      00335          bcf     INTCON,T0IE  ; Clock good, diable TMR0 interrupts
00E7 1683      00336          bsf     STATUS,RP0
00E7 1683      00337          endif
00E8 1283      00338          bcf     STATUS,RP0  ; select Bank0 to read Ports
00E9 1003      00339          bcf     STATUS,C
00EA 1886      00340          btfsc   _SDA
00EB 1403      00341          bsf     STATUS,C
00EB 1403      00342          ;
00EC 0D8E      00343          rlf     DataByte, F  ; left shift data ( MSB first)
00ED 0B8F      00344          decfsz  BitCount, F
00EE 28D5      00345          goto    RcvNextBit
00EE 28D5      00346          ;
00EE 28D5      00347          ; Generate ACK bit if not last byte to be read,
00EE 28D5      00348          ; if last byte Generate NACK ; do not send ACK on last byte, main routine will send a STOP bit
00EE 28D5      00349          ;
00EF 1683      00350          bsf     STATUS,RP0
00F0 1006      00351          bcf     _SCL
00F1 1086      00352          bcf     _SDA          ; ACK by pulling SDA low
00F2 1911      00353          btfsc   _Last_Byte_Rcv
00F3 1486      00354          bsf     _SDA          ; if last byte, send NACK by setting SDA high
00F4 210B      00355          call    Delay47uSec  ; guarantee min LOW TIME tLOW & Setup time
00F5 1406      00356          bsf     _SCL
00F6 210D      00357          call    Delay40uSec  ; guarantee min HIGH TIME tHIGH
00F7           00358 RcvEnd:
00F7 1006      00359          bcf     _SCL          ; reset clock
00F7 1006      00360
00F8 1190      00361          bcf     _Rcv_Progress ; reset TXMT bit in Bus Status
00F9 1690      00362          bsf     _Rcv_Success ; transmission successful
00FA 1390      00363          bcf     _ACK_Error   ; ACK OK
00FA 1390      00364
00FB 0008      00365          return
00FB 0008      00366
00FB 0008      00367          if _CLOCK_STRETCH_CHECK
00FB 0008      00368          ;*****
00FB 0008      00369          ; Fatal Error On I2C Bus
00FB 0008      00370          ;
00FB 0008      00371          ; Slave pulling clock for too long or if SCL Line is stuck low.

```

```

00372 ; This occurs if during Transmission, SCL is stuck low for period longer than approx 1mS
00373 ; and TMR0 times out ( approx 4096 cycles : 256 * 16 -- prescaler of 16).
00374 ;
00375 ;*****
00376
00FC 00377 Bus_Fatal_Error:
00378
00379 ; disable TMR0 Interrupt
00380 ;
00FC 128B 00381 bcf INTCON,T0IE ; disable TMR0 interrupts, until next TXMT try
00382
00383 RELEASE_BUS
00FD 1683 M bsf STATUS,RP0 ; select Bank1
00FE 1486 M bsf _SDA ; tristate SDA
00FF 1406 M bsf _SCL ; tristate SCL
M ; bcf _Bus_Busy ; Bus Not Busy, TEMP ????, set/clear on Start & Stop
00384 ;
00385 ; Set the Bus_Status Bits appropriately
00386 ;
0100 1490 00387 bsf _Abort ; transmission was aborted
0101 1710 00388 bsf _Fatal_Error ; FATAL Error occured
0102 1110 00389 bcf _Txmt_Progress ; Transmission Is Not in Progress
0103 1210 00390 bcf _Txmt_Success ; Transmission Unsuccessful
00391 ;
0104 205F 00392 call TxmtStopBit ; Try sending a STOP bit, may be not successful
00393 ;
0105 0008 00394 return
00395 ;
00396 ;*****
00397 endif
00398
00399
00400 ;*****
00401 ; General Purpose Delay Routines
00402 ;
00403 ; Delay4uS is wait loop for 4.0 uSec
00404 ; Delay47uS is wait loop for 4.7 uSec
00405 ; Delay50uS is wait loop for 5.0 uSec
00406 ;
00407 ;*****
00408 ;
00409
0106 00410 Delay50uSec:
0106 3006 00411 movlw ((_50uS_Delay-5)/3 + 1)
0107 00412 DlyK
0107 0092 00413 movwf DelayCount
0108 0B92 00414 decfsz DelayCount, F

```

```

0109 2908      00415      goto    $-1
010A 0008      00416      return
                00417      ;
010B          00418 Delay47uSec:
010B 3004      00419      movlw   ((_47uS_Delay-8)/3 + 1)
010C 2907      00420      goto    DlyK
                00421      ;
010D          00422 Delay40uSec:
010D 3003      00423      movlw   ((_40uS_Delay-8)/3 + 1)
010E 2907      00424      goto    DlyK
                00425      ;
                00426      ;*****
0109          00109      endif
                00110      ;
                00111      ;*****
                00112      ;
                00113      ;
010F          00114 ReadSlave1:
                00115      ;
                00116      ;
                00117      ; EEPROM (24C04) may be in write mode (busy), check for ACK by sending a control byte
                00118      ;
                00119      LOAD_ADDR_8  _Slave_1_Addr
                M
010F 1011      M          bcf    _10BitAddr    ; Set for 8 Bit Address Mode
0110 30A0      M          movlw   (0xA0 & 0xff)
0111 008C      M          movwf   SlaveAddr
                M
0112          00120 wait1:
                00121      I2C_TEST_DEVICE
                M
0112 2011      M          call   IsSlaveActive  ; TEMP ????: Assembler Error with this MACRO
                M
0113 1F11      00122      btfss  _SlaveActive  ; See If slave is responding
0114 2912      00123      goto   wait1        ; if stuck forever, recover from WDT, can use other schemes
0115 0064      00124      clrwdt
                00125      I2C_READ_SUB  8, DataBegin+1, 0x50
                M
0116 1091      M          bcf    _Slave_RW      ; set for write operation
0117 2057      M          call   TxmtStartBit  ; send START bit
0118 206B      M          call   Txmt_Slave_Addr ; if successful, then _Txmt_Success bit is set
                M
0119 3050      M          movlw   0x50
011A 008E      M          movwf   DataByte    ; START address of EEPROM(slave 1)
011B 2095      M          call   SendData    ; write sub address
                M ;
                M ; do not send STOP after this, use REPEATED START condition

```

```

M ;
M
M          I2C_READ 8, DataBegin+1
M
M
011C 3007      M          movlw   (8 -1)
011D 0096      M          movwf   tempCount          ; -1 because, the last byte is used out of loop
011E 3021      M          movlw   DataBegin+1
011F 0084      M          movwf   FSR                ; FIFO destination address pointer
M
0120 2039      M          call    _i2c_block_read
M
M
M
00126 ;
00127 ; Read 8 bytes of data from Slave 2 starting from Sub-Address 0x60
00128 ;
00129          LOAD_ADDR_8  _Slave_2_Addr
M
0121 1011      M          bcf     _10BitAddr      ; Set for 8 Bit Address Mode
0122 30AC      M          movlw   (0xAC & 0xFF)
0123 008C      M          movwf   SlaveAddr
M
0124          00130 wait2:
00131          I2C_TEST_DEVICE
M
0124 2011      M          call    IsSlaveActive   ; TEMP ????: Assembler Error with this MACRO
M
0125 1F11      00132          btfss   _SlaveActive   ; See If slave is responding
0126 2924      00133          goto    wait2          ; if stuck forever, recover from WDT, can use other schemes
0127 0064      00134          clrwdt
00135          I2C_READ_SUB 8, DataBegin+1, 0x60
M
0128 1091      M          bcf     _Slave_RW        ; set for write operation
0129 2057      M          call    TxmtStartBit    ; send START bit
012A 206B      M          call    Txmt_Slave_Addr ; if successful, then _Txmt_Success bit is set
M
012B 3060      M          movlw   0x60
012C 008E      M          movwf   DataByte        ; START address of EEPROM(slave 1)
012D 2095      M          call    SendData        ; write sub address
M ;
M ; do not send STOP after this, use REPEATED START condition
M ;
M
M          I2C_READ 8,          DataBegin+1
M
M

```

```

012E 3007      M          movlw   (8 -1)
012F 0096      M          movwf   tempCount           ; -1 because, the last byte is used out of loop
0130 3021      M          movlw   DataBegin+1
0131 0084      M          movwf   FSR                 ; FIFO destination address pointer
              M
0132 2039      M          call    _i2c_block_read
              M
              M
              M
00136
00137
0133 0008      M          00138      return
              M          00139      ;
00140      ;*****
00141
0134          M          00142 ReadSlave3:
              M          00143
00144          M          LOAD_ADDR_8  _Slave_3_Addr
              M
0134 1011      M          bcf     _10BitAddr      ; Set for 8 Bit Address Mode
0135 30D6      M          movlw   (0xD6 & 0xff)
0136 008C      M          movwf   SlaveAddr
              M
0137          M          00145 wait3:
              M          00146          I2C_TEST_DEVICE
              M
0137 2011      M          call    IsSlaveActive   ; TEMP ????: Assembler Error with this MACRO
              M
0138 1F11      M          00147          btfss  _SlaveActive   ; See If slave is responding
0139 2937      M          00148          goto   wait3         ; if stuck forever, recover from WDT, can use other schemes
013A 0064      M          00149          clrwdt
00150          M          I2C_READ_SUB 8, DataBegin, 0
              M
013B 1091      M          bcf     _Slave_RW       ; set for write operation
013C 2057      M          call    TxmtStartBit    ; send START bit
013D 206B      M          call    Txmt_Slave_Addr ; if successful, then _Txmt_Success bit is set
              M
013E 3000      M          movlw   0
013F 008E      M          movwf   DataByte       ; START address of EEPROM(slave 1)
0140 2095      M          call    SendData        ; write sub address
              M
              M          ;
              M          ; do not send STOP after this, use REPEATED START condition
              M          ;
              M
              M          I2C_READ 8, DataBegin
              M
              M

```



```

0141 3007      M          movlw   (8 -1)
0142 0096      M          movwf   tempCount      ; -1 because, the last byte is used out of loop
0143 3020      M          movlw   DataBegin
0144 0084      M          movwf   FSR              ; FIFO destination address pointer
              M
0145 2039      M          call    _i2c_block_read
              M
              M
              M
0146 0008      M          00151 ;
              M          00152
              M          00153      return
              M          00154
              M          00155 ;*****
              M          00156 ;
              M          00157 ;          Fill Data Buffer With Test Data ( 8 bytes of 0x55, 0xAA pattern)
              M          00158 ;
              M          00159 ;*****
              M          00160
0147          00161 FillDataBuf:
              M          00162
0147 3000      M          00163      movlw   0x00          ; start address location of EEPROM array
0148 00A0      M          00164      movwf   DataBegin      ; 1st byte of data to be sent is start address
0149 3021      M          00165      movlw   DataBegin+1    ; data starts following address (RAM Pointer)
014A 0084      M          00166      movwf   FSR
014B 3008      M          00167      movlw   8              ; fill RAM with 8 bytes , this data is written to EEPROM (slave)
014C 009A      M          00168      movwf   byteCount
014D 3055      M          00169      movlw   0x55          ; pattern to fill with is 0x55 & 0xAA
014E 009B      M          00170      movwf   HoldData
014F          00171 X1:
014F 099B      M          00172      comf   HoldData, F
0150 081B      M          00173      movf   HoldData,W
0151 0080      M          00174      movwf   INDF
0152 0A84      M          00175      incf   FSR, F          ; point to next location
0153 0B9A      M          00176      decfsz byteCount, F
0154 294F      M          00177      goto   X1
0155 0008      M          00178      return
              M          00179 ;
              M          00180 ;*****
              M          00181 ;
              M          00182 ;          Main Routine (Test Program)
              M          00183 ;
              M          00184 ;          SINGLE MASTER, MULTIPLE SLAVES
              M          00185 ;
              M          00186 ;*****
              M          00187
0156          00188 Start:

```

```

0156 204D      00189      call    InitI2CBus_Master      ; initialize I2C Bus
0157 178B      00190      bsf     INTCON,GIE             ; enable global interrupts
                                00191      ;
                                00192      ;
0158 2147      00193      call    FillDataBuf           ; fill data buffer with 8 bytes of data (0x55, 0xAA)
                                00194      ;
                                00195      ; Use high level Macro to send 9 bytes to Slave (1 & 2 : TWO 24C04) of 8 bit Addr
                                00196      ;
                                00197      ; Write 9 bytes to Slave 1, starting at RAM addr pointer DataBegin
                                00198      ;
                                00199      ;
0159 1810      00200      btfsc  _Bus_Busy ; is Bus Free, ie.has a start & stop bit been detected (only for multi master system)
015A 2959      00201      goto   $-1                    ; a very simple test, unused for now
                                00202      ;
                                00203      LOAD_ADDR_8  _Slave_1_Addr
                                M
015B 1011      M          bcf     _10BitAddr      ; Set for 8 Bit Address Mode
015C 30A0      M          movlw   (0xA0 & 0xff)
015D 008C      M          movwf   SlaveAddr
                                M
                                00204      I2C_WR  0x09, DataBegin
                                M
015E 3009      M          movlw   0x09
015F 0096      M          movwf   tempCount
0160 3020      M          movlw   DataBegin
0161 0084      M          movwf   FSR
                                M
0162 2019      M          call    _i2c_block_write
0163 205F      M          call    TxmtStopBit    ; Issue a stop bit for slave to end transmission
                                M
                                00205      ;
                                00206      ; Write 8 bytes of Data to slave 2 starting at slaves memory address 0x30
                                00207      ;
                                00208      ;
0164 1810      00209      btfsc  _Bus_Busy ; is Bus Free, ie. has a start & stop bit been detected (only for multi master system)
0165 2964      00210      goto   $-1                    ; a very simple test, unused for now
                                00211      ;
                                00212      LOAD_ADDR_8  _Slave_2_Addr
                                M
                                M          bcf     _10BitAddr      ; Set for 8 Bit Address Mode
0166 1011      M          movlw   (0xAC & 0xff)
0167 30AC      M          movwf   SlaveAddr
                                M
                                00213      I2C_WR_SUB  0x08, DataBegin+1, 0x30
                                M
0169 3009      M          movlw   (0x08 + 1)
016A 0096      M          movwf   tempCount

```

```

M
016B 3020      M          movlw   (DataBegin+1 - 1)
016C 0084      M          movwf   FSR
M
016D 0800      M          movf    INDF,W
016E 0097      M          movwf   StoreTemp_1      ; temporarily store contents of (_SourcePointer_ -1)
016F 3030      M          movlw   0x30
0170 0080      M          movwf   INDF          ; store temporarily the sub-address at (_SourcePointer_ -1)
M
0171 2019      M          call    _i2c_block_write ; write _BYTES_+1 block of data
M
0172 0817      M          movf    StoreTemp_1,W
0173 00A0      M          movwf   (DataBegin+1 - 1) ; restore contents of (_SourcePointer_ - 1)
M
0174 205F      M          call    TxmtStopBit    ; Issue a stop bit for slave to end transmission
M
0175 210F      M          call    ReadSlave1    ; read a byte from slave from current address
00214
00215
00216 ;
00217      LOAD_ADDR_8  _Slave_3_Addr
M
0176 1011      M          bcf     _10BitAddr      ; Set for 8 Bit Address Mode
0177 30D6      M          movlw   (0xD6 & 0xFF)
0178 008C      M          movwf   SlaveAddr
M
0179 30CC      M          movlw   0xCC
017A 00A0      M          movwf   DataBegin
00218
00219      I2C_WR_SUB  0x01,DataBegin, 0x33
00220
M
017B 3002      M          movlw   (0x01 + 1)
017C 0096      M          movwf   tempCount
M
017D 301F      M          movlw   (DataBegin - 1)
017E 0084      M          movwf   FSR
M
017F 0800      M          movf    INDF,W
0180 0097      M          movwf   StoreTemp_1      ; temporarily store contents of (_SourcePointer_ -1)
0181 3033      M          movlw   0x33
0182 0080      M          movwf   INDF          ; store temporarily the sub-address at (_SourcePointer_ -1)
M
0183 2019      M          call    _i2c_block_write ; write _BYTES_+1 block of data
M
0184 0817      M          movf    StoreTemp_1,W
0185 009F      M          movwf   (DataBegin - 1) ; restore contents of (_SourcePointer_ - 1)
M
0186 205F      M          call    TxmtStopBit    ; Issue a stop bit for slave to end transmission
M

```

```

0187 2134      00221 ;
                00222      call   ReadSlave3          ; Read From Slave PIC
                00223 ;
                00224
0188 0064      00225 self   clrwdt
0189 2988      00226      goto   self
                00227 ;
                00228 ;*****
                00229
                00230      END

```

MEMORY USAGE MAP ('X' = Used, '-' = Unused)

```

0000 : X--XXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX
0040 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX
0080 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX
00C0 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX
0100 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX
0140 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX
0180 : XXXXXXXXXXXX-----

```

All other memory blocks unused.

```

Program Memory Words Used:  391
Program Memory Words Free:  633

```

```

Errors   :    0
Warnings :    0 reported,    0 suppressed
Messages :    0 reported,    4 suppressed

```



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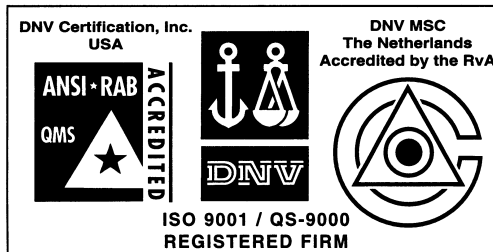
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